# The Area Method, Rigorous Proofs of Lemmas in Hilbert's Style Axiom System 

Pedro Quaresma<br>Department of Mathematics<br>University of Coimbra, Portugal<br>\&<br>Predrag Janičić<br>Faculty of Mathematics<br>University of Belgrade, Serbia

# The Area Method, Rigorous Proofs of Lemmas in Hilbert's Style Axiom System 

Pedro Quaresma<br>CISUC/Department of Mathematics<br>University of Coimbra<br>3001-454 Coimbra, Portugal<br>E-mail: pedro@mat.uc.pt

Predrag Janičić<br>Faculty of Mathematics<br>University of Belgrade<br>Studentski $\operatorname{trg} 16$<br>11000 Belgrade, Serbia<br>e-mail: janicic@matf.bg.ac.rs

October, 2009


#### Abstract

The area method for Euclidean constructive geometry was proposed by Chou et al. in early 1990's. The method produces human-readable proofs and can efficiently prove many nontrivial theorems. It can be considered as one of the most interesting and most successful methods in geometry theorem proving and probably the most successful in the domain of automated production of readable proofs.

In this research report, we focus on the rigorous proofs of all the lemmas of the area method. This text is meant as a support text for the article, The Area Method: a Recapitulation, by Predrag Janičić, Julien Narboux and Pedro Quaresma, submitted for publication in the Journal of Automated Reasoning, in October 2009.


## Chapter 1

## Introduction

There are two major families of methods in automated reasoning in geometry: algebraic style and synthetic style methods.

Algebraic style has its roots in the work of Descartes and in the translation of geometry problems to algebraic problems. The automation of the proving process along this line began with the quantifier elimination method of Tarski [21] and since then had many improvements [8]. The characteristic set method, also known as Wu's method [24, 2], the elimination method [23], the Gröbner basis method [15, 16], and the Clifford algebra approach [17] are examples of practical methods based on the algebraic approach. All these methods have in common an algebraic style, unrelated to traditional, synthetic geometry methods, and they do not provide human-readable proofs. Namely, they deal with polynomials that are often extremely complex for a human to understand, and also with no direct link to the geometrical contents.

The second approach to the automated theorem proving in geometry focuses on synthetic proofs, with an attempt to automate the traditional proving methods. Many of these methods add auxiliary elements to the geometric configuration considered, so that a certain postulates could apply. This usually leads to a combinatorial explosion of the search space. The challenge is to control the combinatorial explosion and to develop suitable heuristics in order to avoid unnecessary construction steps. Examples of synthetic proof methods include approaches by Gelertner [10], Nevis [19], Elcock [9], Greeno et al. [11], Coelho and Pereira [7], Chou, Gao, and Zhang [3, 6].

In this paper we focus on the area method, an efficient semi-algebraic method for a fragment of Euclidean geometry, developed by Chou, Gao, and Zhang [3, 4, 5]. This method enables implementing efficient provers capable of generating human readable proofs. These proofs often differ from the traditional, Hilbert-style, synthetic proofs, but still they are often concise, consisting of steps that are directly related to the geometrical contents involved and hence can be easily understood by a mathematician.

The main idea of the area method is to express the hypotheses of a theorem using a set of starting ("free") points and a set of constructive statements each of them introducing a new point, and to express the conclusion by an equality between polynomials in some geometric quantities (without considering Cartesian coordinates). The proof is developed by eliminating, in reverse order, the points introduced before, using for that purpose a set of appropriate lemmas. After eliminating all the introduced points, the conclusion of the theorem collapses to an equation between two rational expressions involving only free points. This equation can
be further simplified to involve only independent variables. If the expressions on the two sides are equal, the statement is valid, otherwise it is invalid. All proof steps generated by the area method are expressed in terms of applications of high-level geometry lemmas and expression simplifications.

Although the basic idea of the method is simple, implementing it is a very challenging task because of a number of details that has to be dealt with. To our knowledge, apart from the original implementation by the authors who first proposed the area method, there are only three implementations more. These three implementations were made independently and in different contexts:

- within a tool for storing and exploring mathematical knowledge (Theorema [1]) — implemented by Judite Robu [20].
- within a generic proof assistant (Coq [22]) — implemented by Julien Narboux [18];
- within a dynamic geometry tool (GCLC [12]) — implemented by Predrag Janičić and Pedro Quaresma [14];

The implementations of the method can efficiently find proofs of a range of non-trivial theorems, including theorems due to Ceva, Menelaus, Gauss, Pappus, and Thales.

In this research report, we focus on the rigorous proofs of all the lemmas of the area method. This is meant as a support text for the article, The Area Method Revisited, by Predrag Janičić, Julien Narboux and Pedro Quaresma [13].

In the rest of the research report, we will use capital letters to denote points in the plane. We denote by $\overline{A B}$ the length of the oriented segment from $A$ to $B$ and we denote by $\triangle A B C$ the triangle with vertices $A, B$, and $C$.

Overview of the Research Report The research report is organized as follows: After this introduction, we proceed, in Section 2, explaining the area method in detail, presenting the rigorous proofs of all its lemmas.

## Chapter 2

## A Description of the Area Method

The geometrical quantities used within the area method can be defined in Hilbert style geometry, but they also require axioms of the theory of real numbers.

The notion of the ratio of directed parallel segments relies on the notion of orientation of segments, (it holds that $\overline{A B}=-\overline{B A}$ ). The ratio of two directed segments is considered only if they belong to two parallel lines.

DEFINITION 1: (Ratio of directed parallel segments) For four collinear points $P, Q, A$, and $B$, such that $A \neq B$, the ratio of directed parallel segments, denoted $\overline{\overline{P Q}}$ is a real number. If $C$ and $D$ are points such that $A B C D$ is a parallelogram and $P, Q$ are on the line $C D$, then

$$
\frac{\overline{P Q}}{\overline{A B}}=\frac{\overline{P Q}}{\overline{D C}}
$$

The notion of signed areas relies on the notion of orientation of triangles.
DEFINITION 2: (Signed Area) The signed area of triangle $A B C$, denoted $S_{A B C}$, is the area of the triangle with a sign depending on its orientation in the plane: if it is positive, then $S_{A B C}$ is positive, otherwise it is negative.

The Pythagoras difference is a generalization of the Pythagoras equality regarding the three sides of a right triangle, to an expression applicable to any triangle.

DEFINITION 3: (Pythagoras difference) For three points $A, B$, and $C$, the Pythagoras difference, denoted $\mathcal{P}_{A B C}$, is defined in the following way:

$$
\mathcal{P}_{A B C}=\overline{A B}^{2}+\overline{C B}^{2}-\overline{A C}^{2}
$$

In addition to this basic definitions, there are some others that should be introduced.
DEFINITION 4: The signed area of a quadrilateral $A B C D$ is defined as $\mathcal{S}_{A B C D}=\mathcal{S}_{A B C}+$ $\mathcal{S}_{A C D}$.

Note that, more generally, we can define the signed area of an oriented $n$-polygon $A_{1} A_{2} \ldots A_{n}$,
( $n \geq 3$ ) to be:

$$
\mathcal{S}_{A_{1} A_{2} \ldots A_{n}}=\sum_{i=3}^{n} \mathcal{S}_{A_{1} A_{i-1} A_{i}} .
$$

DEFINITION 5: For a quadrilateral $A B C D, \mathcal{P}_{A B C D}$, is defined as follows:

$$
\mathcal{P}_{A B C D}=\mathcal{P}_{A B D}-\mathcal{P}_{C B D}=\overline{A B}^{2}+\overline{C D}^{2}-\overline{B C}^{2}-\overline{D A}^{2} .
$$

### 2.1 Geometric Constructions

The area method is used for proving constructive geometric conjectures: statements about properties of objects constructed by some fixed set of elementary constructions. In this section we first describe the set of available construction steps and then the set of conjectures that can be expressed.

All constructions supported by the area method are expressed in terms of the involved points. Therefore, only lines and circles determined by specific points can be used (rather then arbitrarily chosen lines and circles). Then, the key constructions steps are those introducing new points. For a construction steps to be well-defined, certain conditions may be required. These conditions are called non-degeneracy condition (ndg-conditions). The degree of freedom tells us if a point is free (degree bigger than 0 ), or not.

In the following text, we will denote by (Line U V ) a line such that the points $U$ and $V$ belong to it and we will denote by (Cir O U ) a circle such that its center is point O and such that the point U belongs to it.

Given below is the list of elementary constructions in the area methods, along with the corresponding ndg-conditions and the degrees of freedom of the constructed points.

ECS1 construction of an arbitrary point U; we denote this construction step by (Point U). ndg-condition: -
degree of freedom for $\mathrm{U}: 2$
ECS2 construction of a point Y such that it is the intersection of two lines (Line U V) and (Line P Q); we denote this construction step by (Inter Y (Line U V) (Line P Q)) ndg-condition: $U V \nVdash P Q ; U \neq V ; P \neq Q$.
degree of freedom for $\mathrm{Y}: 0$
ECS3 construction of a point $Y$ such that it is a foot from a given point $P$ to (Line $U$ V); we denote this construction step by (Foot Y P (Line U V)). ndg-condition: $U \neq V$
degree of freedom for Y : 0
ECS4 construction of a point $Y$ on the line passing through point $W$ and parallel to (LINE U V ), such that $\overline{W Y}=r \overline{U V}$, where $r$ can be a rational number, a rational expression
in geometric quantities, or a variable; we denote this construction step by (Pratio Y W (Line U V) r).
ndg-condition: $U \neq V$; if $r$ is a rational expression in geometric quantities then the denominator of $r$ should not be zero.
degree of freedom for $\mathrm{Y}: 0$, if $r$ is a fixed quantity; 1 , if $r$ is a variable.
ECS5 construction of a point $Y$ on the line passing through point $U$ and perpendicular to (Line U V), such that $r=\frac{4 \mathcal{S}_{U V Y}}{\mathcal{P}_{U V U}}$, where $r$ can be a rational number, a rational expression in geometric quantities, or a variable; we denote this construction step by (Tratio Y (Line U V) r).
ndg-condition: $U \neq V$; if $r$ is a rational expression in geometric quantities then the denominator of $r$ should not be zero.
degree of freedom for $\mathrm{Y}: 0$, if $r$ is a fixed quantity; 1 , if $r$ is a variable.
The above set of constructions is sufficient for expressing many constructions based on ruler and compass, but not all of them. For instance, an arbitrary line cannot be constructed by the above construction steps. Still, we can construct two arbitrary points and then implicitly the line going through these points.

### 2.1.1 Constructive Geometric Statements

In the area method, geometric statement have a specific form.
DEFINITION 6: (Constructive Geometric Statement) A constructive geometric statement, is a list $S=\left(C_{1}, C_{2}, \ldots, C_{n}, G\right)$ where $C_{i}$, for $1 \leq i \leq n$, are elementary construction steps, and the conclusion of the statement, $G$, is of the form $E_{1}=E_{2}$, where $E_{1}$ and $E_{2}$ are polynomials in geometric quantities of the points introduced by the steps $C_{i}$.

We denote the class of all constructive geometric statement by $\mathbf{C}$.
For a statement $S=\left(C_{1}, C_{2}, \ldots, C_{n},\left(E_{1}=E_{2}\right)\right)$ from $\mathbf{C}$, the ndg-condition is the set of ndg-conditions of the steps $C_{i}$ plus the condition that the denominators of the length ratios in $E_{1}$ and $E_{2}$ are not equal to zero.

Note that the area method cannot deal with inequalities in its conclusion statement, $G$.

### 2.2 Properties of Geometric Quantities \& Elimination Lemmas

We present here the properties of geometric quantities, required by the area method. We follow the material from [3, 4, 5, 25], but in a reorganized, more methodological form.

## Properties of the Ratio of Directed Parallel Segments

For any points $A, B, P$, and $Q$ we have the following properties.
Lemma 1: $\frac{\overline{P Q}}{A B}=-\frac{\overline{Q P}}{A B}=\frac{\overline{Q P}}{B A}=-\frac{\overline{P Q}}{B A}$.
Lemma 2: $\frac{\overline{P Q}}{A B}=0$ iff $P=Q$.

Lemma 3: $\frac{\overline{P Q}}{\overline{A B}} \frac{\overline{A B}}{\overline{P Q}}=1$.
Lemma 4: $\frac{\overline{A P}}{\overline{A B}}+\frac{\overline{P B}}{\overline{A B}}=1$.
Lemma 5: For any real number there is a unique point $P$ which is collinear with $A$ and $B$, and satisfies $\frac{\overline{A P}}{\overline{A B}}=r$.

Lemma 6: If points $C$ and $D$ are on line $A B, A \neq B$ and $P$ is any point not on line $A B$ then, $\frac{\mathcal{S}_{P C D}}{\mathcal{S}_{P A B}}=\frac{\overline{C D}}{\overline{A B}}$.
Lemma 7: (EL1) (The Co-side Theorem) Let $M$ be the intersection of two non-parallel lines $A B$ and $P Q$ and $Q \neq M$. Then it holds that $\overline{\overline{P M}}=\frac{\mathcal{S}_{P A B}}{\mathcal{S}_{Q A B}} ; \frac{\overline{P M}}{\overline{P Q}}=\frac{\mathcal{S}_{P A B}}{\mathcal{S}_{P A Q B}} ; \frac{\overline{Q M}}{\overline{P Q}}=\frac{\mathcal{S}_{Q A B}}{\mathcal{S}_{P A Q B}}$.

Since $\mathcal{S}_{P A B}$ and $\mathcal{S}_{Q A B}$ cannot both be zero, we always assume that the nonzero one is the denominator. Also note that $\overline{P Q} \neq 0$ since $A B \nVdash P Q$.

The lemma EL1 is the first of a set of important lemmas for the area method, called elimination lemmas (EL). The proofs of any conjecture in $\mathbf{C}$ will be based in this lemmas. Notice that the point $M$, which was introduced by a given construction, can be eliminated by the substitution from the ratio of directed parallel segments by a ratio of two signed areas, not involving $M$.

## Properties of the Signed Area

For any points $A, B, C$ and $D$, we have the following properties.

Lemma 8: $\mathcal{S}_{A B C}=\mathcal{S}_{C A B}=\mathcal{S}_{B C A}=-\mathcal{S}_{A C B}=-\mathcal{S}_{B A C}=-\mathcal{S}_{C B A}$.
Lemma 9: $\mathcal{S}_{A B C}=0$ iff $A, B$, and $C$ are collinear.
Lemma 10: $\mathcal{S}_{A B C}=\mathcal{S}_{A B D}+\mathcal{S}_{A D C}+\mathcal{S}_{D B C}$.
Lemma 11: $P Q \| A B$ iff $\mathcal{S}_{P A B}=\mathcal{S}_{Q A B}$, i.e., iff $\mathcal{S}_{P A Q B}=0$.
Lemma 12: $\mathcal{S}_{A B C D}=\mathcal{S}_{A B D}+\mathcal{S}_{B C D}$.
Lemma 13: $\mathcal{S}_{A B C D}=\mathcal{S}_{B C D A}=\mathcal{S}_{C D A B}=\mathcal{S}_{D A B C}=-\mathcal{S}_{A D C B}=-\mathcal{S}_{D C B A}=-\mathcal{S}_{C B A D}=$ $-\mathcal{S}_{B A D C}$.

Lemma 14: Let $A B C D$ be a parallelogram and $P$ be an arbitrary point. Then it holds that $\mathcal{S}_{A B C}=\mathcal{S}_{P A B}+\mathcal{S}_{P C D}, \mathcal{S}_{P A B}=\mathcal{S}_{P D A C}=\mathcal{S}_{P D B C}$, and $\mathcal{S}_{P A B}=\mathcal{S}_{P C D}-\mathcal{S}_{A C D}=$ $\mathcal{S}_{P D A C}$.

Lemma 15: Let $A B C D$ be a parallelogram, $P$ and $Q$ be two arbitrary points. Then it holds that $\mathcal{S}_{A P Q}+\mathcal{S}_{C P Q}=\mathcal{S}_{B P Q}+\mathcal{S}_{D P Q}$ or $\mathcal{S}_{P A Q B}=\mathcal{S}_{P D Q C}$.

Lemma 16: Let $R$ be a point on the line $P Q$. Then for any two points $A$ and $B$ it holds that $\mathcal{S}_{R A B}=\frac{\overline{P R}}{\overline{P Q}} \mathcal{S}_{Q A B}+\frac{\overline{R Q}}{\overline{P Q}} \mathcal{S}_{P A B}$.

## Properties of the Pythagoras Difference

For any points $A, B, C$ and $D$ we have the following properties.

Lemma 17: $\mathcal{P}_{A A B}=0$.
Lemma 18: $\mathcal{P}_{A B C}=\mathcal{P}_{C B A}$.
Lemma 19: $\mathcal{P}_{A B A}=2 \overline{A B}^{2}$.
Lemma 20: If $A, B$, and $C$ are collinear then, $\mathcal{P}_{A B C}=2 \overline{B A} \overline{B C}$.
Lemma 21: $\mathcal{P}_{A B C D}=-\mathcal{P}_{A D C B}=\mathcal{P}_{B A D C}=-\mathcal{P}_{B C D A}=\mathcal{P}_{C D A B}=-\mathcal{P}_{C B A D}=\mathcal{P}_{D C B A}=$ $-\mathcal{P}_{D A B C}$.

Lemma 22: $A B \perp B C$ iff $\mathcal{P}_{A B C}=0$.
Lemma 23: $A B \perp C D$ iff $\mathcal{P}_{A C D}=\mathcal{P}_{B C D}$ or $\mathcal{P}_{A C B D}=0$.
Lemma 24: Let $D$ be the foot of the perpendicular from a point $P$ to a line $A B$. Then, it holds that

$$
\frac{\overline{A D}}{\overline{D B}}=\frac{\mathcal{P}_{P A B}}{\mathcal{P}_{P B A}}, \quad \frac{\overline{A D}}{\overline{A B}}=\frac{\mathcal{P}_{P A B}}{2 \overline{A B}^{2}}, \quad \frac{\overline{D B}}{\overline{A B}}=\frac{\mathcal{P}_{P B A}}{2 \overline{A B}^{2}}
$$

Lemma 25: Let $A B$ and $P Q$ be two non-perpendicular lines, and $Y$ be the intersection of line $P Q$ and the line passing through $A$ and perpendicular to $A B$. Then, it holds that

$$
\frac{\overline{P Y}}{\overline{Q Y}}=\frac{\mathcal{P}_{P A B}}{\mathcal{P}_{Q A B}}, \quad \frac{\overline{P Y}}{\overline{P Q}}=\frac{\mathcal{P}_{P A B}}{\mathcal{P}_{P A Q B}}, \quad \frac{\overline{Q Y}}{\overline{P Q}}=\frac{\mathcal{P}_{Q A B}}{\mathcal{P}_{P A Q B}}
$$

Lemma 26: Let $R$ be a point on the line $P Q$ such that $r_{1}=\frac{\overline{P R}}{\overline{P Q}}, r_{2}=\frac{\overline{R Q}}{\overline{P Q}}$. Then, for points $A, B$, it holds that

$$
\begin{aligned}
\mathcal{P}_{R A B} & =r_{1} \mathcal{P}_{Q A B}+r_{2} \mathcal{P}_{P A B} \\
\mathcal{P}_{A R B} & =r_{1} \mathcal{P}_{A Q B}+r_{2} \mathcal{P}_{A P B}-r_{1} r_{2} \mathcal{P}_{P Q P}
\end{aligned}
$$

Lemma 27: Let $A B C D$ be a parallelogram. Then for any points $P$ and $Q$, it holds that

$$
\begin{aligned}
& \mathcal{P}_{A P Q}+\mathcal{P}_{C P Q}=\mathcal{P}_{B P Q}+\mathcal{P}_{D P Q} \text { or } \mathcal{P}_{A P B Q}=\mathcal{P}_{D P C Q} \\
& \mathcal{P}_{P A Q}+\mathcal{P}_{P C Q}=\mathcal{P}_{P B Q}+\mathcal{P}_{P D Q}+2 \mathcal{P}_{B A D} .
\end{aligned}
$$

## Elimination Lemmas

Considering the constructions steps we need only to eliminate points introduced by four constructions (ECS2 to ECS5), from three kinds of geometric quantities.

Lemma 28: Let $G(Y)$ be one of the following geometric quantities: $\mathcal{S}_{A B Y}, \mathcal{S}_{A B C Y}, \mathcal{P}_{A B Y}$, or $\mathcal{P}_{A B C Y}$ for distinct points $A, B, C$, and $Y$. For three collinear points $Y, U$, and $V$ it holds

$$
\begin{equation*}
G(Y)=\frac{\overline{U Y}}{\overline{U V}} G(V)+\frac{\overline{Y V}}{\overline{U V}} G(U) \tag{2.1}
\end{equation*}
$$

The above result follows from lemmas 16 and 25 . Note that, given lemmas $8,13,18,21$, all signed areas and Pythagoras differences (not of the form $\mathcal{P}_{A Y B}$ ) involving $Y$ can be reduced to quantities of the form $\mathcal{S}_{A B Y}, \mathcal{S}_{A B C Y}, \mathcal{P}_{A B Y}$, or $\mathcal{P}_{A B C Y}$.

We call $G(Y)$ a linear geometric quantity for the variable $Y$. Elimination procedures for all linear geometric quantities are similar for constructions ECS2 to ECS4.

We now present the set of elimination lemmas that in conjunction with the already presented lemma EL1 are the base for the area method's algorithm.

Lemma 29: (EL2) Let $G(Y)$ be a linear geometric quantity and point $Y$ is introduced by the construction (Pratio Y W (Line U V) r). Then it holds

$$
G(Y)=G(W)+r(G(V)-G(U))
$$

Lemma 30: (EL3) Let $G(Y)$ be a linear geometric quantity and point $Y$ is introduced by the construction (Inter Y (Line U V) (Line P Q). Then it holds

$$
G(Y)=\frac{\mathcal{S}_{U P Q} G(V)-\mathcal{S}_{V P Q} G(U)}{\mathcal{S}_{U P V Q}}
$$

Lemma 31: (EL4) Let $G(Y)$ be a linear geometric quantity $\left(\neq \mathcal{P}_{A Y B}\right)$ and point $Y$ is introduced by the construction (Fоot Y P (Line U V)). Then it holds

$$
G(Y)=\frac{\mathcal{P}_{P U V} G(V)+\mathcal{P}_{P V U} G(U)}{\mathcal{P}_{U V U}}
$$

Lemma 32: (EL5) Let $G(Y)=\mathcal{P}_{A Y B}$ and point $Y$ is introduced by the construction (Foot Y P (Line U V)). Then it holds

$$
G(Y)=\frac{\mathcal{P}_{P U V}}{\mathcal{P}_{U V U}} G(V)+\frac{\mathcal{P}_{P V U}}{\mathcal{P}_{U V U}} G(U)-\frac{\mathcal{P}_{P U V} \times \mathcal{P}_{P V U}}{\mathcal{P}_{U V U}} .
$$

Lemma 33: (EL6) Let $G(Y)=\mathcal{P}_{A Y B}$ and point $Y$ is introduced by the construction (InTER Y (Line U V) (Line P Q)). Then it holds

$$
G(Y)=\frac{\mathcal{S}_{U P Q}}{\mathcal{S}_{U P V Q}} G(V)+\frac{\mathcal{S}_{V P Q}}{\mathcal{S}_{U P V Q}} G(U)-\frac{\mathcal{S}_{U P Q} \times \mathcal{S}_{V P Q} \times \mathcal{P}_{U V U}}{\mathcal{S}_{U P V Q}^{2}}
$$

Lemma 34: (EL7) Let point $Y$ be introduced by (Pratio Y W (Line U V) r). Then it holds:

$$
\mathcal{P}_{A Y B}=\mathcal{P}_{A W B}+r\left(\mathcal{P}_{A V B}-\mathcal{P}_{A U B}+2 \mathcal{P}_{W U V}\right)-r(1-r) \mathcal{P}_{U V U} .
$$

Lemma 35: (EL8) Let point $Y$ be introduced by (Tratio Y (Line P Q) r). Then it holds:

$$
\mathcal{S}_{A B Y}=\mathcal{S}_{A B P}-\frac{r}{4} \mathcal{P}_{P A Q B}
$$

Lemma 36: (EL9) Let point $Y$ be introduced by (Tratio Y (Line P Q) r). Then it holds:

$$
\mathcal{P}_{A B Y}=\mathcal{P}_{A B P}-4 r \mathcal{S}_{P A Q B} .
$$

Lemma 37: (EL10) Let point $Y$ be introduced by (Tratio Y (Line P Q) r). Then it holds

$$
\mathcal{P}_{A Y B}=\mathcal{P}_{A P B}+r^{2} \mathcal{P}_{P Q P}-4 r\left(\mathcal{S}_{A P Q}+\mathcal{S}_{B P Q}\right) .
$$

Now we consider how to eliminate points from the ratio of directed parallel segments.

Lemma 38: (EL11) Let $Y$ be introduced by (Inter Y (Line U V) (Line P Q)). Then it holds

$$
\frac{\overline{A Y}}{\overline{C D}}= \begin{cases}\frac{\mathcal{S}_{A P Q}}{\mathcal{S}_{P D D}} & \text { if } A \text { is on } U V \\ \frac{\mathcal{S}_{A U V}}{\mathcal{S}_{C U D V}} & \text { otherwise }\end{cases}
$$

Lemma 39: (EL12) Let $Y$ be introduced by (Foot Y P (Line U V)). We assume $D \neq U$; otherwise interchange $U$ and $V$. Then it holds

$$
\frac{\overline{A Y}}{\overline{C D}}= \begin{cases}\frac{\mathcal{P}_{P C A D}}{P_{C D C}} & \text { if } A \text { is on } U V \\ \frac{S_{A U V}}{\mathcal{S}_{C U D V}} & \text { otherwise }\end{cases}
$$

Lemma 40: (EL13) Let $Y$ be introduced by (Pratio Y R (Line P Q) r). Then it holds

$$
\frac{\overline{A Y}}{\overline{C D}}= \begin{cases}\frac{\frac{\overline{A R}}{}}{\frac{A_{Q}}{P Q}} & \text { if } A \text { is on } R Y \\ \frac{\mathcal{S}_{A P R Q}}{\mathcal{S}_{C P D Q}} & \text { otherwise }\end{cases}
$$

Lemma 41: (EL14) Let $Y$ be introduced by (Tratio $Y$ (Line P Q) r). Then it holds

$$
\frac{\overline{A Y}}{\overline{C D}}= \begin{cases}\frac{\mathcal{S}_{A P Q}-\frac{r}{4} \mathcal{P}_{P Q P}}{S_{C P D Q}} & \text { if } A \text { is on } P Y \\ \frac{\mathcal{P}_{A P Q}}{\mathcal{P}_{C P D Q}} & \text { otherwise }\end{cases}
$$

The information on the elimination lemmas is summarized on table 2.1.

|  |  | Geometric Quantities |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | $\mathcal{P}_{\text {AY }}$ | $\mathcal{P}_{\text {ABY }} \quad \mathcal{P}_{A B C Y}$ | $\mathcal{S}_{A B Y} \quad \mathcal{S}_{A B C Y}$ | $\frac{\overline{A Y}}{\overline{C D}}$ | $\frac{\overline{A Y}}{\overline{B Y}}$ |
| $\stackrel{8}{8}$ | ECS2 | EL5 | EL3 |  | EL11 | EL1 |
| \% | ECS3 | EL6 | EL4 |  | EL12 |  |
| \% | ECS4 | EL7 | EL2 |  | EL13 |  |
| $\bigcirc$ | ECS5 | EL10 | EL9 | EL8 | EL14 |  |
| Elimination Lemmas |  |  |  |  |  |  |

Table 2.1: Elimination Lemmas

## Free Points and Area Coordinates

The elementary construction step ECS1 introduces arbitrary points on the geometric construction, these points are the free points on which all other objects are based. For a geometric statement $S=\left(C_{1}, C_{2}, \ldots, C_{m},\left(E_{1}=E_{2}\right)\right)$, after eliminating all the non-free points introduced by $C_{i}$ from $E_{1}$ and $E_{2}$ using the lemmas of the preceding subsections, we obtain two rational expressions $E_{1}^{\prime}$ and $E_{2}^{\prime}$ in signed areas and Pythagoras differences of free points, and numerical constants.

Most often this simply lead to equations that are trivially true. However, if the remaining geometric quantities are, in a generic case, not independent, e.g. for any four points $A, B, C$, and $D$ we have

$$
\mathcal{S}_{A B C}=\mathcal{S}_{A B D}+\mathcal{S}_{A D C}+\mathcal{S}_{D B C}
$$

We thus need to reduce $E_{1}^{\prime}$ and $E_{2}^{\prime}$ to expressions in independent variables. To do that, we sometimes need to use area coordinates.

DEFINITION 7: Let $A, O, U$, and $V$ be four points such that $O, U$, and $V$ are not collinear. The area coordinates of $A$ with respect to $O U V$ are

$$
x_{A}=\frac{\mathcal{S}_{O U A}}{\mathcal{S}_{O U V}}, \quad y_{A}=\frac{\mathcal{S}_{O A V}}{\mathcal{S}_{O U V}}, \quad z_{A}=\frac{\mathcal{S}_{A U V}}{\mathcal{S}_{O U V}} .
$$

It is clear that $x_{A}+y_{A}+z_{A}=1$.
It is clear that the points in the plane are in a one to one correspondence with their area coordinates. To represent $E_{1}$ and $E_{2}$ as expressions in independent variables, we first introduce three new points $O, U$, and $V$, such that, $U O \perp O V$, and $\frac{\overline{O U}}{O V}=1$. We will reduce $E_{1}$ and $E_{2}$ to expressions in the area coordinates of the free points with respect to $O U V$.

For any free points $A, B$, and $C$, the following lemmas hold.
Lemma 42: $\mathcal{S}_{A B C}=\frac{\left(\mathcal{S}_{O V B}-\mathcal{S}_{O V C}\right) \mathcal{S}_{O U A}+\left(\mathcal{S}_{O V C}-\mathcal{S}_{O V A}\right) \mathcal{S}_{O U B}+\left(\mathcal{S}_{O V A}-\mathcal{S}_{O V B}\right) \mathcal{S}_{O U C}}{\mathcal{S}_{O U V}}$.
Lemma 43: $\overline{A B}^{2}=\frac{\overline{O U}^{2}\left(\mathcal{S}_{O V A}-\mathcal{S}_{O V B}\right)^{2}}{S_{O U V}^{2}}+\frac{\overline{O V}^{2}\left(\mathcal{S}_{O U A}-\mathcal{S}_{O U B}\right)^{2}}{S_{O U V}^{2}}$.
Lemma 44: $S_{O U V}^{2}=\frac{\overline{O U}^{2} \times \overline{O V}^{2}}{4}$.
Using lemmas 42 to 44 , expressions $E_{1}$ and $E_{2}$ can be written as expressions in $\overline{O U}, \overline{O V}$, and the area coordinates of the free points. Since the area coordinates of free points are independent, $E_{1}=E_{2}$ iff $E_{1}$ and $E_{2}$ are identical.

### 2.3 Rigorous Proofs

### 2.3.1 Proof of the Properties of the Ratio of Directed Parallel Segments

In the following we will present all the proofs of the lemmas presented above. To a better reading, the statements of the lemmas will be repeated.

We assume $A \neq B$ whenever needed.
Lemma 1: $\frac{\overline{P Q}}{\overline{A B}}=-\frac{\overline{Q P}}{A B}=\frac{\overline{Q P}}{\overline{B A}}=-\frac{\overline{P Q}}{\overline{B A}}$.

Proof of Lemma 1 By definition of length of an oriented segment, we have that $\overline{A B}=-\overline{B A}$, then it holds

$$
\frac{\overline{P Q}}{\overline{A B}}=\frac{-\overline{Q P}}{\overline{A B}}=-\frac{\overline{Q P}}{\overline{A B}}=-\frac{\overline{Q P}}{-\overline{B A}}=\frac{\overline{Q P}}{\overline{B A}}=\frac{-\overline{P Q}}{\overline{B A}}=-\frac{\overline{P Q}}{\overline{B A}} .
$$

Q.E.D.

Lemma 2: $\frac{\overline{P Q}}{\overline{A B}}=0$ iff $P=Q$.

Proof of Lemma 2 By definition of length of a segment we have that $\overline{P Q}=0$ iff $P=Q$, then it holds $\frac{\overline{P Q}}{\overline{A B}}=0$ iff $P=Q$.
Q.E.D.

Lemma 3: $\frac{\overline{P Q}}{\overline{A B}} \frac{\overline{A B}}{\overline{P Q}}=1$.

Proof of Lemma 3 By the definition of ratio of directed segments, and given the fact that we are considering the same segments (without changing orientations), we can consider $\frac{\overline{P Q}}{\overline{A B}}=r$, then it holds $\frac{\overline{P Q}}{\overline{A B}} \frac{\overline{A B}}{\overline{P Q}}=r \cdot \frac{1}{r}=1$.
Q.E.D.

Lemma 4: $\frac{\overline{A P}}{\overline{A B}}+\frac{\overline{P B}}{\overline{A B}}=1$.
Proof of Lemma 4 By the definition of ratio of directed segments, the points $A, B$ and $P$ are collinear.

Then we have, $\overline{A P}+\overline{P B}=\overline{A B}$ and

$$
\frac{\overline{A P}}{\overline{A B}}+\frac{\overline{P B}}{\overline{A B}}=\frac{\overline{A P}+\overline{P B}}{\overline{A B}}=\frac{\overline{A B}}{\overline{A B}}=1
$$

Q.E.D.


Figure 2.1:

Lemma 5: For any real number there is a unique point $P$ which is collinear with $A$ and $B$, and satisfies $\frac{\overline{A P}}{A B}=r$.

Proof of Lemma 5 By the definition of ratio of directed segments, the points $A, B$ and $P$ are collinear, them the conclusion is a direct consequence of the bijection between the set of real numbers and the real line (any straight line).
Q.E.D.

Lemma 6: If points $C$ and $D$ are on line $A B, A \neq B$ and $P$ is any point not on line $A B$ then, $\frac{\mathcal{S}_{P C D}}{\mathcal{S}_{P A B}}=\frac{\overline{C D}}{A B}$.

## Proof of Lemma 6



Figure 2.2: Areas, Ratios relationship
Let $S$ is the point on $A B$ such that $P S$ is perpendicular to $A B$ ( $\overline{P S}$ is the height of both triangles) then it holds

$$
\begin{aligned}
& \left|\mathcal{S}_{P C D}\right|=\frac{\overline{\overline{C C}} \overline{P S}}{2} \text { and }\left|\mathcal{S}_{P A B}\right|=\frac{\overline{A B} \overline{P S}}{2} \text { so } \\
& \qquad \frac{\left|\mathcal{S}_{P C D}\right|}{\left|\mathcal{S}_{P A B}\right|}=\frac{\overline{D C} \overline{P S}}{2} \frac{2}{\overline{A B} \overline{P S}}=\frac{\overline{D C}}{\overline{A B}} .
\end{aligned}
$$

Since $\triangle P C D$ and $\triangle P A B$ have different orientations, and $\overline{C D}$ and $\overline{A B}$ have opposite directions, then

$$
\frac{\mathcal{S}_{P C D}}{-\mathcal{S}_{P A B}}=\frac{-\overline{C D}}{\overline{A B}} .
$$

Q.E.D.

Lemma 7: (EL1) (The Co-side Theorem) Let $M$ be the intersection of two non-parallel lines $A B$ and $P Q$ and $Q \neq M$. Then it holds that $\frac{\overline{P M}}{\overline{Q M}}=\frac{\mathcal{S}_{P A B}}{\mathcal{S}_{Q A B}} ; \frac{\overline{P M}}{\overline{P Q}}=\frac{\mathcal{S}_{P A B}}{\mathcal{S}_{P A Q B}} ; \frac{\overline{Q M}}{\overline{P Q}}=\frac{\mathcal{S}_{Q A B}}{\mathcal{S}_{P A Q B}}$.


Figure 2.3: Co-side Theorem

## Proof of Lemma 7

The figure 2.3 gives several possible cases (in ordered geometries). The proof here presented, which is essentially for unordered geometry, is valid for all cases [25]. For the first formula, take a point $R$ on $A B$ such that $\overline{A B}=\overline{M R}$; them, by lemma 6 , we have $\frac{\mathcal{S}_{P M R}}{\mathcal{S}_{P A B}}=$ $\frac{M R}{A B}=1 \Leftrightarrow \mathcal{S}_{P M R}=\mathcal{S}_{P A B}$, the same applies for the point $Q, \mathcal{S}_{Q M R}=\mathcal{S}_{Q A B}$. So:


Figure 2.4:

$$
\frac{\mathcal{S}_{P A B}}{\mathcal{S}_{Q A B}}=\frac{\mathcal{S}_{P M R}}{\mathcal{S}_{Q M R}}
$$

Now by a direct application of lemma 6 , making $A=Q, B=D=M$, and $C=P$ we have:

$$
\frac{\mathcal{S}_{P M R}}{\mathcal{S}_{Q M R}}=\frac{\mathcal{S}_{R P M}}{\mathcal{S}_{R Q M}}=\frac{\overline{P M}}{\overline{Q M}}
$$

in conclusion

$$
\frac{\mathcal{S}_{P A B}}{\mathcal{S}_{Q A B}}=\frac{\mathcal{S}_{P M R}}{\mathcal{S}_{Q M R}}=\frac{\overline{P M}}{\overline{Q M}}
$$

The others formulas are a consequence of this first one.
Q.E.D.

### 2.3.2 Proofs of the Properties of the Signed Area

Lemma 8: For any points $A, B, C$, and $D$, it holds that $\mathcal{S}_{A B C}=\mathcal{S}_{C A B}=\mathcal{S}_{B C A}=-\mathcal{S}_{A C B}=$ $-\mathcal{S}_{B A C}=-\mathcal{S}_{C B A}$.


Figure 2.5:

Proof of Lemma 8 It is a direct consequence of the definition of signed area. The $\triangle A B C$, $\triangle C A B$ and $\triangle B C A$ all have the same orientation.

The $\triangle A C B, \triangle B A C$ and $\triangle C B A$ have the opposite orientation (from $\triangle A B C$ ).
Q.E.D.

Lemma 9: For any points $A, B, C$, and $D$, it holds that $\mathcal{S}_{A B C}=0$ iff $A, B$, and $C$ are collinear.

## Proof of Lemma 9



Figure 2.6: Lemma 9
$\mathcal{S}_{A B C}=0 \Leftrightarrow\left|\mathcal{S}_{A B C}\right|=0 \Leftrightarrow \frac{b \cdot h}{2}=0 \Leftrightarrow b=0$ or $h=0 \Leftrightarrow A=B$ or $C$ belongs to line $A B \Leftrightarrow A, B, C$ are collinear.
Q.E.D.

Lemma 10: $\mathcal{S}_{A B C}=\mathcal{S}_{A B D}+\mathcal{S}_{A D C}+\mathcal{S}_{D B C}$.

## Proof of Lemma 10



Figure 2.7: Lemma 10
Let $P$ be the intersection of $A C$ and $B D$, let we denote $\mathcal{S}_{A B P}=a, \mathcal{S}_{B C P}=b, \mathcal{S}_{P C D}=c$, and $\mathcal{S}_{P D A}=d$, them we have

$$
\begin{array}{rlrl}
\mathcal{S}_{A B C} & =\mathcal{S}_{A B D}+\mathcal{S}_{A D C}+\mathcal{S}_{D B C} & & \Leftrightarrow \\
a+b & =(a+d)-(d+c)+(c+b) & \Leftrightarrow \\
a+b & =a+d-d-c+c+b & & \Leftrightarrow \\
a+b & =a+b &
\end{array}
$$

Q.E.D.

Lemma 11: $P Q \| A B$ iff $\mathcal{S}_{P A B}=\mathcal{S}_{Q A B}$, i.e., iff $\mathcal{S}_{P A Q B}=0$.

## Proof of Lemma 11



Figure 2.8: Lemma 11
Proof of $P Q \| A B$ iff $\mathcal{S}_{P A B}=\mathcal{S}_{Q A B}$.
We must state that the two triangles, $\triangle P A B$ and $\triangle Q A B$ have the same orientation.
i) $P Q \| A B \Rightarrow \mathcal{S}_{P A B}=\mathcal{S}_{Q A B}$ :

If $P Q \| A B$ then the two triangles $\triangle P A B$ and $\triangle Q A B$ have equal heights $\overline{P H^{\prime}}=\overline{P H^{\prime \prime}}$, given the fact that they also have a common base $(A B)$, then we have $\mathcal{S}_{P A B}=\mathcal{S}_{Q A B}$.
ii) $P Q \| A B \Leftarrow \mathcal{S}_{P A B}=\mathcal{S}_{Q A B}$ :

If $\mathcal{S}_{P A B}=\mathcal{S}_{Q A B}$ we have $\frac{1}{2} \overline{A B} h^{\prime}=\frac{1}{2} \overline{A B} h^{\prime \prime}$, then $h^{\prime}=h^{\prime \prime}$, so the points $P$ and $Q$ are at the same distance from the line $A B$, that is, $P Q \| A B$.

Proof of $P Q \| A B$ iff $\mathcal{S}_{P A Q B}=0$.
i) $P Q \| A B \Rightarrow \mathcal{S}_{P A Q B}=0$ :
$\mathcal{S}_{P A Q B} \stackrel{\text { def }}{=} \mathcal{S}_{P A Q}+\mathcal{S}_{P Q B}$, given the fact that this two triangles have a common base, $P Q$, equal heights, $h^{\prime}=h^{\prime \prime}$, but opposite orientation, we have $\mathcal{S}_{P A Q}+\mathcal{S}_{P Q B}=0$.
ii) $P Q \| A B \Leftarrow \mathcal{S}_{P A Q B}=0$ :
$\mathcal{S}_{P A Q B}=0 \stackrel{\text { def }}{\Leftrightarrow} \mathcal{S}_{P A Q}+\mathcal{S}_{P Q B}=0 \Leftrightarrow \mathcal{S}_{P A Q}=-\mathcal{S}_{P Q B} \stackrel{\text { lemma }}{\Leftrightarrow}{ }^{8} \mathcal{S}_{P Q A}=\mathcal{S}_{P Q B} \stackrel{\text { def }}{\Leftrightarrow} \frac{1}{2} \overline{P Q} h^{\prime}=$ $\frac{1}{2} \overline{P Q} h^{\prime \prime} \Rightarrow P Q \| A B$.
Q.E.D.

Lemma 12: $\mathcal{S}_{A B C D}=\mathcal{S}_{A B D}+\mathcal{S}_{B C D}$.

## Proof of Lemma 12

Let $P$ be the intersection of $A C$ and $B D$, let we denote $\mathcal{S}_{A B P}=a, \mathcal{S}_{B C P}=b, \mathcal{S}_{P C D}=c$, and $\mathcal{S}_{P D A}=d$, them by lemmas 8 and 10 we have:

$$
\begin{aligned}
\mathcal{S}_{A B C}+\mathcal{S}_{A C D} & =(a+b+c+d-a-d)+(a+b+c+d-b-c) \\
& =(a+d+b+c-d-c)+(a+d+b+c-a-b) \\
& =\mathcal{S}_{A B D}+\mathcal{S}_{B C D}
\end{aligned}
$$



Figure 2.9: Lemma 12
Q.E.D.

Lemma 13: $\mathcal{S}_{A B C D}=\mathcal{S}_{B C D A}=\mathcal{S}_{C D A B}=\mathcal{S}_{D A B C}=-\mathcal{S}_{A D C B}=-\mathcal{S}_{D C B A}=-\mathcal{S}_{C B A D}=$ $-\mathcal{S}_{\text {BADC }}$.

Proof of Lemma 13 This is a direct consequence of definition 4 and lemma 8.
Q.E.D.

Lemma 14: Let $A B C D$ be a parallelogram and $P$ be an arbitrary point. Then it holds that $\mathcal{S}_{A B C}=\mathcal{S}_{P A B}+\mathcal{S}_{P C D}, \mathcal{S}_{P A B}=\mathcal{S}_{P D A C}=\mathcal{S}_{P D B C}$, and $\mathcal{S}_{P A B}=\mathcal{S}_{P C D}-\mathcal{S}_{A C D}=$ $\mathcal{S}_{\text {PDAC }}$.

## Proof of Lemma 14



Figure 2.10: Lemma 14
Let $S$ is a point on $B C$ such that $P S$ is parallel to $C D$. By lemma 11, it holds that $A D\left\|B C \Leftrightarrow \mathcal{S}_{A B C}=\mathcal{S}_{D B C}, P S\right\| C D \Leftrightarrow \mathcal{S}_{P D C}=\mathcal{S}_{S D C} \Leftrightarrow \mathcal{S}_{P C D}=-\mathcal{S}_{D C S}$, and $P S \|$ $A B \Leftrightarrow \mathcal{S}_{P A B}=\mathcal{S}_{S A B}, A D \| B S \Leftrightarrow \mathcal{S}_{A B S}=\mathcal{S}_{D B S} \Leftrightarrow \mathcal{S}_{P A B}=\mathcal{S}_{S A B}=\mathcal{S}_{A B S}=\mathcal{S}_{D B S} \Leftrightarrow$ $\mathcal{S}_{P A B}=\mathcal{S}_{D B S}$. Therefore, $\mathcal{S}_{P A B}+\mathcal{S}_{P D C}=\mathcal{S}_{D B S}-\mathcal{S}_{D C S}$. This proves the first formula. The second formula is a consequence of the first one.
Q.E.D.

Lemma 15: Let $A B C D$ be a parallelogram, $P$ and $Q$ be two arbitrary points. Then it holds that $\mathcal{S}_{A P Q}+\mathcal{S}_{C P Q}=\mathcal{S}_{B P Q}+\mathcal{S}_{D P Q}$ or $\mathcal{S}_{P A Q B}=\mathcal{S}_{P D Q C}$.

## Proof of Lemma 15



Figure 2.11:

Notice that $\triangle A P Q$ and $\triangle B P Q$ have the same orientation, different from the orientation of $\triangle C P Q$ and $\triangle D P Q$. Let $O$ be the intersection of $A C$ and $B D$. Since $O$ is the midpoint of $A C$, by lemma $16, \mathcal{S}_{A P Q}+\mathcal{S}_{C P Q}=2 \mathcal{S}_{O P Q}$. For the same reason, $\mathcal{S}_{B P Q}+\mathcal{S}_{D P Q}=2 \mathcal{S}_{O P Q}$. We have proved the first formula, the second formula is just another form of the first one.
Q.E.D.

Lemma 16: Let $R$ be a point on the line $P Q$. Then for any two points $A$ and $B$ it holds that $\mathcal{S}_{R A B}=\frac{\overline{P R}}{\overline{P Q}} \mathcal{S}_{Q A B}+\frac{\overline{R Q}}{\overline{P Q}} \mathcal{S}_{P A B}$.

## Proof of Lemma 16



Figure 2.12: Lemma 16

Let $s=\mathcal{S}_{A B P Q}$, then $\mathcal{S}_{R A B}=s-\mathcal{S}_{A R Q}-\mathcal{S}_{B P R}$ (all these triangles have the same orientation)


Figure 2.13: Lemma 16a
let $\frac{\overline{P R}}{\overline{P Q}}=\lambda$, then, by lemma 6 (with $\mathrm{P}:=\mathrm{A} ; \mathrm{A}:=\mathrm{P} ; \mathrm{B}:=\mathrm{Q} ; \mathrm{D}:=\mathrm{Q} ; \mathrm{C}:=\mathrm{R}$ ), we have

$$
\frac{\mathcal{S}_{A R Q}}{\mathcal{S}_{A P Q}}=\frac{\overline{R Q}}{\overline{P Q}}=\frac{\overline{P Q}-\overline{P R}}{\overline{P Q}}=(1-\lambda) \Leftrightarrow \mathcal{S}_{A R Q}=(1-\lambda) \mathcal{S}_{A P Q}
$$

and,


Figure 2.14: Lemma 16b

$$
\frac{\mathcal{S}_{B P R}}{\mathcal{S}_{B P Q}}=\frac{\overline{P R}}{\overline{P Q}}=\lambda \Leftrightarrow \mathcal{S}_{B P R}=\lambda \mathcal{S}_{B P Q}
$$

then

$$
\begin{aligned}
\mathcal{S}_{R A B} & =s-\mathcal{S}_{A R Q}-\mathcal{S}_{B P R} \\
& =s-(1-\lambda) \mathcal{S}_{A P Q}-\lambda \mathcal{S}_{B P Q} \\
& =s-(1-\lambda)\left(s-\mathcal{S}_{P A B}\right)-\lambda\left(s-\mathcal{S}_{Q A B}\right) \\
& =s-s+\lambda s+\mathcal{S}_{P A B}-\lambda \mathcal{S}_{P A B}-\lambda s+\lambda \mathcal{S}_{Q A B} \\
& =\lambda \mathcal{S}_{Q A B}+(1-\lambda) \mathcal{S}_{P A B} \\
& =\frac{\overline{P R}}{\overline{P Q}} \mathcal{S}_{Q A B}+\frac{\overline{R Q}}{\overline{P Q}} \mathcal{S}_{P A B}
\end{aligned}
$$

Q.E.D.

### 2.3.3 Proofs of the Properties of the Pythagoras Difference

We begin by introducing the concept of co-area of triangles [4].
Given a triangle $A B C$, we construct the square $A B P Q$ such that $\mathcal{S}_{A B C}$ and $\mathcal{S}_{A B P Q}$ have the same sign (see figure 2.15).


Figure 2.15: Co-area of a triangle
The Co-area of a triangle $A B C, \mathcal{C}_{A B C}$, is a real number such that

$$
\mathcal{C}_{A B C}= \begin{cases}\nabla A C Q, & \text { if } \angle A \leq 90^{\circ} ; \\ -\nabla A C Q, & \text { if } \angle A>90^{\circ} ;\end{cases}
$$

where $\nabla A B C$ is the area of triangle $A B C$.
For a triangle $A B C$ we have $\mathcal{C}_{A B C}+\mathcal{C}_{B A C}=\nabla B P C+\nabla A C Q=\nabla A B P Q / 2=A B^{2} / 2$.
Considering the different permutations of the vertices of the triangle $A B C$ we can conclude that, $\mathcal{P}_{A B C}=4 \mathcal{C}_{A B C}$.

Lemma 17: $\mathcal{P}_{A A B}=0$.

## Proof of Lemma 17

$$
\mathcal{P}_{A A B}=\overline{A A}^{2}+\overline{C A}^{2}-\overline{A C}^{2}=0+\overline{A C}^{2}-\overline{A C}^{2}=0
$$

given the fact that $\overline{C A}^{2}=\overline{C A} \times \overline{C A}=-\overline{A C} \times(-\overline{A C})=\overline{A C}^{2}$.
Q.E.D.

Lemma 18: $\mathcal{P}_{A B C}=\mathcal{P}_{C B A}$.

## Proof of Lemma 18

$$
\mathcal{P}_{A B C}=\overline{A B}^{2}+\overline{C B}^{2}-\overline{A C}^{2}=\overline{C B}^{2}+\overline{A B}^{2}-\overline{C A}^{2}=\mathcal{P}_{C B A}
$$

Q.E.D.

Lemma 19: $\mathcal{P}_{A B A}=2 \overline{A B}^{2}$.
Proof of Lemma 19

$$
\mathcal{P}_{A B A}=\overline{A B}^{2}+\overline{A B}^{2}-\overline{A A}^{2}=2 \overline{A B}^{2}
$$

Q.E.D.

Lemma 20: If $A, B$, and $C$ are collinear then, $\mathcal{P}_{A B C}=2 \overline{B A} \overline{B C}$.
Proof of Lemma 20 Since $A, B$, and $C$ are collinear, we have $\overline{A B}+\overline{B C}=\overline{A C}$ and therefore it holds that:

$$
\begin{aligned}
\mathcal{P}_{A B C} & =\overline{A B}^{2}+\overline{C B}^{2}-{\overline{A C^{2}}}^{2} \\
& =\overline{A B}^{2}+\overline{B C}^{2}+2 \overline{A B} \overline{B C}-2 \overline{A B} \overline{B C}-\overline{A C}^{2} \\
& =\left(\overline{A B}+\overline{B C}^{2}-2 \overline{A B} \overline{B C}-\overline{A C}^{2}\right. \\
& =-2 \overline{A B} \overline{B C} \\
& =2 \overline{B A} \overline{B C}
\end{aligned}
$$

Q.E.D.

Lemma 21: $\mathcal{P}_{A B C D}=-\mathcal{P}_{A D C B}=\mathcal{P}_{B A D C}=-\mathcal{P}_{B C D A}=\mathcal{P}_{C D A B}=-\mathcal{P}_{C B A D}=\mathcal{P}_{D C B A}=$ $-\mathcal{P}_{\text {DABC }}$.

## Proof of Lemma 21

$$
\begin{aligned}
\mathcal{P}_{A D C B} & =\overline{A D}^{2}+\overline{C B}^{2}-\overline{D C}^{2}-\overline{B A}^{2} \\
& =-\overline{A B}^{2}-\overline{C D}^{2}+\overline{B C}^{2}+\overline{D A}^{2} \\
& =-\left(\mathcal{P}_{A B C D}\right) \\
\mathcal{P}_{B A D C} & =\overline{B A}^{2}+\overline{D C}^{2}-\overline{A D}^{2}-\overline{C B}^{2} \\
& =\overline{A B}^{2}+\overline{C D}^{2}-\overline{B C}^{2}-\overline{D A}^{2} \\
& =\mathcal{P}_{A B C D} \\
\mathcal{P}_{B C D A} & =\overline{B C}^{2}+\overline{D A}^{2}-\overline{C D}^{2}-\overline{A B}^{2} \\
& =-\overline{A B}^{2}-\overline{C D}^{2}+\overline{B C}^{2}+\overline{D A}^{2} \\
& =-\left(\mathcal{P}_{A B C D}\right) \\
\mathcal{P}_{C D A B} & =\overline{C D}^{2}+\overline{A B}^{2}-\overline{D A}^{2}-\overline{B C}^{2} \\
& =\overline{A B}^{2}+\overline{C D}^{2}-\overline{B C}^{2}-\overline{D A}^{2} \\
& =\mathcal{P}_{A B C D} \\
\mathcal{P}_{C B A D} & =\overline{C B}^{2}+\overline{B A}^{2}-{\overline{D C^{2}}}^{2} \\
& =-\overline{A B}^{2}-\overline{C D}^{2}+\overline{B C}^{2}+\overline{D A}^{2} \\
& =-\left(\mathcal{P}_{A B C D}\right) \\
\mathcal{P}_{D C B A} & =\overline{D C}^{2}+\overline{B A}^{2}-\overline{C B}^{2}-\overline{A D}^{2} \\
& =\overline{A B}^{2}+\overline{C D}^{2}-\overline{B C}^{2}-\overline{D A}^{2} \\
& =\mathcal{P}_{A B C D} \\
\mathcal{P}_{D A B C} & =\overline{D A}^{2}+\overline{B C}^{2}-\overline{A B}^{2}-\overline{C D}^{2} \\
& =-\overline{A B}^{2}-\overline{C D}^{2}+\overline{B C}^{2}+\overline{D A}^{2} \\
& =-\left(\mathcal{P}_{A B C D}\right)
\end{aligned}
$$

Q.E.D.

Lemma 22: $A B \perp B C$ iff $\mathcal{P}_{A B C}=0$.

## Proof of Lemma 22

$A B \perp B C \Rightarrow \mathcal{P}_{A B C}=0$
If $A B \perp B C$ we have that $A=B$, or $C=B$, or the points $A, B$, and $C$ form a right triangle.

If $A=B$ we have, by lemma $17, \mathcal{P}_{A B C}=\mathcal{P}_{B B C}=0$.
If $C=B$ we have, by lemmas 17 and $18, \mathcal{P}_{A B C}=\mathcal{P}_{A C C}=\mathcal{P}_{C C A}=0$.
If neither the above conditions are met, we have that $\angle B=90^{\circ}$ and $\mathcal{P}_{A B C}=4 \mathcal{C}_{A B C}=$ $\nabla B P C=0$
$A B \perp C D \Leftarrow \mathcal{P}_{A B C}=0$
We consider that $A \neq B \neq C$, we already saw that whenever they are equal the two expressions are equivalent.

Considering the co-area definition we can conclude that $\mathcal{P}_{A B C}=0$ then $\angle B=90^{\circ}$ (if $\mathcal{P}_{A B C}>0$ then $\angle B<90^{0}$, and if $\mathcal{P}_{A B C}<0$ then $\left.\angle B>90^{\circ}\right)$.
Q.E.D.

Lemma 23: $A B \perp C D$ iff $\mathcal{P}_{A C D}=\mathcal{P}_{B C D}$ or $\mathcal{P}_{A C B D}=0$.

## Proof of Lemma 23



Figure 2.16: Lemma 23
Let $P$ be the intersection of lines $A B$ and $C D$, then:

$$
\begin{aligned}
\overline{A D}^{2} & =\overline{A P}^{2}+\overline{P D}^{2}, \quad \overline{A C}^{2}=\overline{A P}^{2}+\overline{P C}^{2} \\
\overline{A D}^{2}-\overline{P D}^{2} & =\overline{A C}^{2}-\overline{P C}^{2} \\
\overline{B D}^{2} & =\overline{B P}^{2}+\overline{P D}^{2} \\
\overline{B C}^{2} & =\overline{B P}^{2}+\overline{P C}^{2} \\
\overline{B D}^{2}-\overline{P D}^{2} & =\overline{B C}^{2}-\overline{P C}^{2} \\
\overline{A D}^{2}-\overline{A C}^{2} & =\overline{P D}^{2}+\overline{P C}^{2} \\
\overline{B D}^{2}-\overline{B C}^{2} & =\overline{P D}^{2}+\overline{P C}^{2} \\
\overline{A D}^{2}-\overline{A C}^{2} & =\overline{B D}^{2}-\overline{B C}^{2}
\end{aligned}
$$

$$
\begin{aligned}
\overline{A C}^{2}-\overline{A D}^{2} & =\overline{B C}^{2}-\overline{B D}^{2} \\
\overline{A C}^{2}+\overline{D C}^{2}-\overline{A D}^{2} & =\overline{B C}^{2}+\overline{D C}^{2}-\overline{B D}^{2} \\
\mathcal{P}_{A C D} & =\mathcal{P}_{B C D}
\end{aligned}
$$

The second equality is a direct consequence of equality just proved, and of the definition 5: $\mathcal{P}_{A C B D}=\mathcal{P}_{A C D}-\mathcal{P}_{B C D}=0$
Q.E.D.

Lemma 24: Let $D$ be the foot of the perpendicular constructed from a point $P$ to a line $A B$. Then, it holds that

$$
\frac{\overline{A D}}{\overline{D B}}=\frac{\mathcal{P}_{P A B}}{\mathcal{P}_{P B A}}, \quad \frac{\overline{A D}}{\overline{A B}}=\frac{\mathcal{P}_{P A B}}{2 \overline{A B}^{2}}, \quad \frac{\overline{D B}}{\overline{A B}}=\frac{\mathcal{P}_{P B A}}{2 \overline{A B}^{2}} .
$$

## Proof of Lemma 24



Figure 2.17: Lemma 24
First equality:

$$
\begin{aligned}
& \frac{\overline{A D}}{\overline{D B}}=\frac{\mathcal{P}_{P A B}}{\mathcal{P}_{P B A}}=\frac{\overline{P A}^{2}+\overline{B A}^{2}-\overline{P B}^{2}}{\overline{P B}^{2}+\overline{A B}^{2}-\overline{P A}^{2}} \\
& A, B \text { and } D \text { are collinear, so } \overline{A B}=\overline{A D}+\overline{D B} \\
& =\frac{\overline{P A}^{2}+\overline{A D}^{2}+\overline{D B}^{2}+2 \overline{A D} \overline{D B}-\overline{P B}^{2}}{\overline{P B}^{2}+\overline{A D}^{2}+\overline{D B}^{2}+2 \overline{A D} \overline{D B}-\overline{P A}^{2}} \\
& A B \perp D P \text { so } \overline{P A}^{2}=\overline{A D}^{2}+\overline{P D}^{2} \text { and } \overline{P B}^{2}=\overline{D B}^{2}+\overline{P D}^{2} \\
& =\frac{\overline{A D}^{2}+\overline{P D}^{2}+\overline{A D}^{2}+\overline{D B}^{2}+2 \overline{A D} \overline{D B}-\left(\overline{D B}^{2}+\overline{P D}^{2}\right)}{\overline{D B}^{2}+\overline{P D}^{2}+\overline{D B}^{2}+2 \overline{A D} \overline{D B}-\left(\overline{A D}^{2}+\overline{P D}^{2}\right)} \\
& =\frac{2 \overline{A D}^{2}+2 \overline{A D} \overline{D B}}{2 \overline{D B}^{2}+2 \overline{A D} \overline{D B}}=\frac{2 \overline{A D}(\overline{A D}+\overline{D B})}{2 \overline{D B}(\overline{A D}+\overline{D B})}=\frac{\overline{A D}}{\overline{D B}}
\end{aligned}
$$

Second equality:

$$
\begin{aligned}
& \frac{\overline{A D}}{\overline{A B}}=\frac{\mathcal{P}_{P A B}}{2 \overline{A B}^{2}}=\frac{\overline{P A}^{2}+\overline{B A}^{2}-\overline{P B}^{2}}{2 \overline{A B}^{2}} \\
& A B \perp D P \text { so } \overline{P A}^{2}=\overline{A D}^{2}+\overline{P D}^{2} \text { and } \overline{P B}^{2}=\overline{D B}^{2}+\overline{P D}^{2}
\end{aligned}
$$

$$
\begin{aligned}
& =\frac{\overline{A D}^{2}+\overline{P D}^{2}+\overline{B A}^{2}-\overline{D B}^{2}-\overline{P D}^{2}}{2 \overline{A B}^{2}} \\
& =\frac{\overline{A D}^{2}+\overline{B A}^{2}-\overline{D B}^{2}}{2 \overline{A B}^{2}}
\end{aligned}
$$

$$
A, B \text { and } D \text { are collinear, so } \overline{A B}=\overline{A D}+\overline{D B}
$$

$$
=\frac{\overline{A D}^{2}+\overline{A D}^{2}+2 \overline{A D} \overline{D B}+\overline{D B}^{2}-\overline{D B}^{2}}{2 \overline{A B}^{2}}
$$

$$
=\frac{2 \overline{A D}(\overline{A D}+\overline{D B})}{2 \overline{A B}^{2}}
$$

$A, B$ and $D$ are collinear, so $\overline{A B}=\overline{A D}+\overline{D B}$

$$
=\frac{\overline{A D} \overline{A B}}{\overline{A B}^{2}}=\frac{\overline{A D}}{\overline{A B}}
$$

The proof of the third equality is similar to this last one.
Q.E.D.

Lemma 25: Let $A B$ and $P Q$ be two non-perpendicular lines, and $Y$ be the intersection of line $P Q$ and the line passing through $A$ and perpendicular to $A B$. Then, it holds that

$$
\frac{\overline{P Y}}{\overline{Q Y}}=\frac{\mathcal{P}_{P A B}}{\mathcal{P}_{Q A B}}, \quad \frac{\overline{P Y}}{\overline{P Q}}=\frac{\mathcal{P}_{P A B}}{\mathcal{P}_{P A Q B}}, \quad \frac{\overline{Q Y}}{\overline{P Q}}=\frac{\mathcal{P}_{Q A B}}{\mathcal{P}_{P A Q B}} .
$$

## Proof of Lemma 25



Figure 2.18: Lemma 25
The first equality is:

$$
\frac{\overline{P Y}}{\overline{Q Y}}=\frac{\mathcal{P}_{P A B}}{\mathcal{P}_{Q A B}}
$$

by lemma 23 with $A:=Q_{1} ; B:=Q ; C:=A ; D:=B$, for $\overline{Q Y}$ and with $A:=P_{1} ; B:=P ; C:=$ $A ; D:=B$, for $\overline{P Y}$, we have:

$$
\begin{aligned}
\frac{\overline{P Y}}{\overline{Q Y}} & =\frac{\mathcal{P}_{P_{1} A B}}{\mathcal{P}_{Q_{1} A B}} \quad P_{1}, Q_{1}, A \text { and } B \text { are collinear } \\
& =\frac{2 \overline{A P_{1}} \overline{A B}}{2 \overline{A Q_{1}}} \overline{\overline{A B}}
\end{aligned}
$$

$$
\begin{aligned}
& =\frac{\overline{A P_{1}}}{\overline{\overline{A Q_{1}}}}=\frac{-\overline{P_{1} A}}{-\overline{Q_{1} A}} \quad \text { by definition of oriented segments } \\
& =\overline{\overline{P_{1} A}} \\
& \overline{\overline{Q_{1} A}}
\end{aligned}
$$

by the co-side theorem, with $P:=P_{1} ; Q:=Q_{1} ; M:=A ; A:=A ; B:=Y$,

$$
=\frac{\mathcal{S}_{P_{1} A Y}}{\mathcal{S}_{Q_{1} A Y}}=\frac{\mathcal{S}_{A Y P_{1}}}{\mathcal{S}_{A Y Q_{1}}}, \quad \text { by lemma } 8
$$

by lemma 11, given the fact that $A Y \| P_{1} P$ and $A Y \| Q_{1} Q$,

$$
=\frac{\mathcal{S}_{P_{1} A Y}}{\mathcal{S}_{Q_{1} A Y}}=\frac{\mathcal{S}_{A Y P_{1}}}{\mathcal{S}_{A Y Q_{1}}}, \quad \text { by lemma } 8
$$

by the co-side theorem, with $P:=P ; Q:=Q ; M:=Y ; A:=Y ; B:=A$,

$$
=\frac{\overline{P Y}}{\overline{Q Y}}
$$

This prove the first equality.
The second equality is:

$$
\frac{\overline{P Y}}{\overline{P Q}}=\frac{\mathcal{P}_{P A B}}{\overline{\mathcal{P}}_{P A Q B}}
$$

$$
\begin{aligned}
\frac{\overline{P Q}}{\overline{\overline{P Y}}} & =\frac{\overline{P Y}+\overline{Y Q}}{\overline{P Y}}, \quad P, Y, \text { and } Q \text { are colinear } \\
& =\frac{\overline{P Y}-\overline{Q Y}}{\overline{P Y}}, \quad \text { by definition of oriented segments } \\
& =\frac{\overline{P Y}}{\overline{P Y}}-\overline{\overline{P Y}} \\
& =1+\frac{\mathcal{P}_{Q A B}}{\mathcal{P}_{P A B}}, \quad \text { by the previous result } \\
& =\frac{\mathcal{P}_{P A B}}{\mathcal{P}_{P A B}}-\frac{\mathcal{P}_{Q A B}}{\mathcal{P}_{P A B}} \\
& =\frac{\mathcal{P}_{P A B}-\mathcal{P}_{Q A B}}{\mathcal{P}_{P A B}} \\
& =\frac{\mathcal{P}_{P A Q B}}{\mathcal{P}_{P A B}}, \quad \text { by definition } 5
\end{aligned}
$$

The proof of the third equality is similar to this last proof.
Q.E.D.

Lemma 26: Let $R$ be a point on the line $P Q$ such that $r_{1}=\frac{\overline{P R}}{\overline{P Q}}, r_{2}=\frac{\overline{R Q}}{\overline{P Q}}$. Then, for points $A, B$, it holds that

$$
\begin{aligned}
& \mathcal{P}_{R A B}=r_{1} \mathcal{P}_{Q A B}+r_{2} \mathcal{P}_{P A B} \\
& \mathcal{P}_{A R B}=r_{1} \mathcal{P}_{A Q B}+r_{2} \mathcal{P}_{A P B}-r_{1} r_{2} \mathcal{P}_{P Q P} .
\end{aligned}
$$

## Proof of Lemma 26



Figure 2.19: Lemma 26
The first equality

$$
\mathcal{P}_{R A B}=r_{1} \mathcal{P}_{Q A B}+r_{2} \mathcal{P}_{P A B}
$$

going to co-areas, considering the square $A B X_{1} X_{2}$ (see figure 2.20 ), we have

$$
\mathcal{C}_{R A B}=r_{1} \mathcal{C}_{Q A B}+r_{2} \mathcal{C}_{P A B}
$$



Figure 2.20: Lemma 26, first equality

$$
\begin{aligned}
\nabla A R X_{2} & =r_{1} \nabla A Q X_{2}+r_{2} \nabla A P X_{2} \\
A X_{2} h_{1} & =\frac{\overline{P R}}{\overline{P Q}} A X_{2} h_{2}+\frac{\overline{R Q}}{\overline{P Q}} A X_{2} h_{3} \\
h_{1} & =\frac{h_{1}-h_{3}}{h_{2}-h_{3}} h_{2}-\frac{h_{2}-h_{1}}{h_{2}-h_{3}} h_{3} \\
h_{1} h_{2}-h_{1} h_{3} & =h_{1} h_{2}-h_{3} h_{2}+h_{2} h_{3}-h_{1} h_{3} \\
h_{1} h_{2}-h_{1} h_{3} & =h_{1} h_{2}-h_{1} h_{3}
\end{aligned}
$$

The second equality

$$
\mathcal{P}_{A R B}=r_{1} \mathcal{P}_{A Q B}+r_{2} \mathcal{P}_{A P B}-r_{1} r_{2} \mathcal{P}_{P Q P}
$$

by definition of Pythagoras difference

$$
\begin{aligned}
& \overline{A R}^{2}+\overline{B R}^{2}-\overline{A B}^{2}= \\
& =r_{1}\left(\overline{A Q}^{2}+\overline{B Q}^{2}-\overline{A B}^{2}\right)+r_{2}\left(\overline{A P}^{2}+\overline{B P}^{2}-\overline{A B}^{2}\right)-r_{1} r_{2} \mathcal{P}_{P Q P} \\
& \begin{aligned}
&\left(\overline{A R}^{2}\right.\left.+\overline{A B}^{2}-\overline{B R}^{2}\right)+2 \overline{B R}^{2}-2 \overline{A B}^{2}= \\
&= r_{1}\left(\left(\overline{A Q}^{2}+\overline{A B}^{2}-\overline{B Q}^{2}\right)+2 \overline{B Q}^{2}-2 \overline{A B}^{2}\right)+r_{2}\left(\left(\overline{A P}^{2}+\overline{A B}^{2}-\overline{B P}^{2}\right)+\right. \\
&\left.\quad+2 \overline{B P}^{2}-2 \overline{A B}^{2}\right)-r_{1} r_{2} \mathcal{P}_{P Q P} \\
& \mathcal{P}_{R A B}+2 \overline{B R}^{2}-2 \overline{A B}^{2}= \\
&= r_{1} \mathcal{P}_{Q A B}+r_{1}\left(2 \overline{B Q}^{2}-2 \overline{A B}^{2}\right)+r_{2} \mathcal{P}_{P A B}+r_{2}\left(2 \overline{B P}^{2}-2 \overline{A B}^{2}\right)- \\
& \quad-r_{1} r_{2} \mathcal{P}_{P Q P}
\end{aligned}
\end{aligned}
$$

by the first equality

$$
2 \overline{B R}^{2}-2 \overline{A B}^{2}=r_{1}\left(2 \overline{B Q}^{2}-2 \overline{A B}^{2}\right)+r_{2}\left(2 \overline{B P}^{2}-2 \overline{A B}^{2}\right)-r_{1} r_{2} \mathcal{P}_{P Q P}
$$

by lemma 19

$$
\begin{aligned}
2\left(\overline{B R}^{2}-\overline{A B}^{2}\right) & =2 r_{1}\left(\overline{B Q}^{2}-\overline{A B}^{2}\right)+2 r_{2}\left(\overline{B P}^{2}-\overline{A B}^{2}\right)-2 r_{1} r_{2} \overline{P Q}^{2} \\
\overline{B R}^{2}-\overline{A B}^{2} & =r_{1} \overline{B Q}^{2}+r_{2} \overline{B P}^{2}-\left(r_{1}+r_{2}\right) \overline{A B}^{2}-r_{1} r_{2} \overline{P Q}^{2}
\end{aligned}
$$

by lemma $4, r_{1}+r_{2}=1$,

$$
\overline{B R}^{2}=\frac{\overline{P R}}{\overline{P Q}} \overline{B Q}^{2}+\frac{\overline{R Q}}{\overline{P Q}} \overline{B P}^{2}-\frac{\overline{P R} \overline{R Q}}{\overline{P Q}^{2}} \overline{P Q}^{2}
$$

$$
\overline{P R} \overline{B Q}^{2}+\overline{R Q} \overline{B P}^{2}-\overline{P Q} \overline{B R}^{2}=\overline{P R} \overline{R Q} \overline{P Q}
$$



Figure 2.21: Lemma 26, second equality
By lemma 22 (see also figure 2.21), we have:

$$
\begin{aligned}
& \overline{B Q}^{2}=\overline{B Z}^{2}+\overline{Q Z}^{2} \\
& \overline{B R}^{2}=\overline{B Z}^{2}+\overline{R Z}^{2} \\
& \overline{B P}^{2}=\overline{B Z}^{2}+\overline{P Z}^{2}
\end{aligned}
$$

so, we have:

$$
\begin{aligned}
\overline{P R}\left(\overline{B Z}^{2}+\overline{Q Z}^{2}\right)+\overline{R Q}\left(\overline{B Z}^{2}+\overline{P Z}^{2}\right)-\overline{P Q}\left(\overline{B Z}^{2}+\overline{R Z}^{2}\right) & =\overline{P R} \overline{R Q} \overline{P Q} \\
(\overline{P R}+\overline{R Q}-\overline{P Q}) \overline{B Z^{2}}+\overline{P R} \overline{Q Z}^{2}+\overline{R Q} \overline{P Z}^{2}-\overline{P Q} \overline{R Z}^{2} & =\overline{P R} \overline{R Q} \overline{P Q}
\end{aligned}
$$

by lemma 4

$$
\overline{P R} \overline{Q Z}^{2}+\overline{R Q} \overline{P Z}^{2}-\overline{P Q} \overline{R Z}^{2}=\overline{P R} \overline{R Q} \overline{P Q}
$$

by lemma 4 we can rewrite the different segments in the following form:

$$
\begin{aligned}
\overline{Q Z} & =-\overline{Z Q} \\
\overline{R Q} & =\overline{R Z}+\overline{Z Q} \\
\overline{P Z} & =\overline{P R}+\overline{R Z} \\
\overline{P Q} & =\overline{P R}+\overline{R Z}+\overline{Q Z}
\end{aligned}
$$

we get:

$$
\begin{aligned}
& \overline{P R} \overline{Z Q}^{2}+(\overline{R Z}+\overline{Z Q})(\overline{P R}+\overline{R Z})^{2}-(\overline{P R}+\overline{R Z}+\overline{Z Q}) \overline{R Z}^{2}= \\
& =\overline{P R}(\overline{R Z}+\overline{Z Q})(\overline{P R}+\overline{R Z}+\overline{Q Z}) \\
& \overline{P R} \overline{Z Q}^{2}+\overline{P R}^{2} \overline{R Z}+2 \overline{P R} \overline{R Z}^{2}+\overline{R Z}^{3}+\overline{P R}^{2} \overline{Z Q}+2 \overline{P R} \overline{R Z} \overline{Z Q}+ \\
& +\overline{R Z}^{2} \overline{Z Q}-\overline{P R} \overline{R Z}^{2}-\overline{R Z}^{3}-\overline{R Z}^{2} \overline{Z Q}= \\
& =\overline{P R}^{2} \overline{R Z}+\overline{P R} \overline{R Z}^{2}+\overline{P R} \overline{R Z} \overline{Z Q}+\overline{P R}^{2} \overline{Z Q}+\overline{P R} \overline{R Z} \overline{Z Q}+\overline{P R}_{\overline{Z Q}^{2}} \\
& \overline{P R} \overline{R Z} \overline{Z Q}=\overline{P R} \overline{R Z} \overline{Z Q}
\end{aligned}
$$

Q.E.D.

Lemma 27: Let $A B C D$ be a parallelogram. Then for any points $P$ and $Q$, it holds that

$$
\begin{aligned}
& \mathcal{P}_{A P Q}+\mathcal{P}_{C P Q}=\mathcal{P}_{B P Q}+\mathcal{P}_{D P Q} \quad \text { or } \quad \mathcal{P}_{A P B Q}=\mathcal{P}_{D P C Q} \\
& \mathcal{P}_{P A Q}+\mathcal{P}_{P C Q}=\mathcal{P}_{P B Q}+\mathcal{P}_{P D Q}+2 \mathcal{P}_{B A D}
\end{aligned}
$$

Before presenting the proof of this lemma we present the following lemma.
Auxiliary Lemma 1 Let $P$ and $Q$ be the feet of the perpendiculars from point $A$ and $C$ to $B D$. Then $\mathcal{P}_{A B C D}=2 \overline{Q P} \overline{B D}$.

## Proof of Auxiliary Lemma 1

$$
\mathcal{P}_{A B C D}=\mathcal{P}_{A B D}-\mathcal{P}_{C B D}, \quad \text { by definition }
$$

by the lemma 23 with $A:=A ; B:=P ; C:=B ; D:=D$, we have $\mathcal{P}_{A B D}=\mathcal{P}_{P B D}$, and with $A:=C ; B:=Q ; C:=B ; D:=D$, we have $\mathcal{P}_{C B D}=\mathcal{P}_{Q B D}$,

$$
=\mathcal{P}_{P B D}-\mathcal{P}_{Q B D}
$$

by the lemma 20

$$
\begin{aligned}
& =2 \overline{B P} \overline{B D}-\overline{B Q} \overline{B D} \\
& =2 \overline{B D}(\overline{B P}-\overline{B Q}) \\
& =2 \overline{Q P} \overline{B D}
\end{aligned}
$$

## Proof of Lemma 27



Figure 2.22: Lemma 27

$$
\mathcal{P}_{A P Q}+\mathcal{P}_{C P Q}=\mathcal{P}_{B P Q}+\mathcal{P}_{D P Q}
$$

First the equivalence $\mathcal{P}_{A P Q}+\mathcal{P}_{C P Q}=\mathcal{P}_{B P Q}+\mathcal{P}_{D P Q} \Leftrightarrow \mathcal{P}_{A P B Q}=\mathcal{P}_{D P C Q}$

$$
\begin{array}{rlr}
\mathcal{P}_{A P B Q} & =\mathcal{P}_{D P C Q} & \\
\mathcal{P}_{A P Q}-\mathcal{P}_{B P Q} & =\mathcal{P}_{D P Q}-\mathcal{P}_{C P Q} & \text { by definition } 5 \\
\mathcal{P}_{A P Q}+\mathcal{P}_{C P Q} & =\mathcal{P}_{D P Q}+\mathcal{P}_{B P Q} &
\end{array}
$$

Now the equality $\mathcal{P}_{A P B Q}=\mathcal{P}_{D P C Q}$.

$$
\begin{array}{rlrl}
\mathcal{P}_{A P B Q} & =\mathcal{P}_{D P C Q}, & & \text { by lemma } 21 \\
\mathcal{P}_{P A Q B} & =\mathcal{P}_{P D Q C}, & & \text { by auxiliarylemma } 1 \\
2 \overline{Q P} \overline{D C} & =2 \overline{Q P} \overline{A B} &
\end{array}
$$

by hypothesis $A B C D$ is a parallelogram, so $\overline{A B}=\overline{D C}$,

$$
2 \overline{Q P} \overline{A B}=2 \overline{Q P} \overline{A B}
$$

Now the last equality

$$
\begin{aligned}
\mathcal{P}_{P A Q}+\mathcal{P}_{P C Q} & =\mathcal{P}_{P B Q}+\mathcal{P}_{P D Q}+2 \mathcal{P}_{B A D} \\
\mathcal{P}_{P A Q}+\mathcal{P}_{P C Q}-\mathcal{P}_{P B Q}-\mathcal{P}_{P D Q}-2 \mathcal{P}_{B A D} & =0
\end{aligned}
$$

by definition of Pythagoras differences

$$
\begin{aligned}
0 & =\mathcal{P}_{P A Q}+\mathcal{P}_{P C Q}-\mathcal{P}_{P B Q}-\mathcal{P}_{P D Q}-2 \mathcal{P}_{B A D} \\
& =\overline{P A}^{2}+\overline{Q A}^{2}-\overline{P Q}^{2}+\overline{P C}^{2}+\overline{Q C}^{2}-\overline{P Q}^{2}-\overline{P B}^{2}-\overline{Q B}^{2}+\overline{P Q}^{2}- \\
& -\overline{P D}^{2}-\overline{Q D}^{2}+\overline{P Q}^{2}-2 \mathcal{P}_{B A D} \\
& =\overline{P A}^{2}+\overline{Q A}^{2}+\overline{P C}^{2}+\overline{Q C}^{2}-\overline{P B}^{2}-\overline{Q B}^{2}-\overline{P D}^{2}-\overline{Q D}^{2}-2 \mathcal{P}_{B A D} \\
& =\overline{A P}^{2}-\overline{A Q}^{2}+\overline{C P}^{2}-\overline{C Q}^{2}-\overline{B P}^{2}+\overline{B Q}^{2}-\overline{D P}^{2}+\overline{D Q}^{2}+ \\
& +2 \overline{A Q}^{2}+2 \overline{C Q}^{2}-2 \overline{B Q}^{2}-2 \overline{D Q}^{2}-2 \mathcal{P}_{B A D}
\end{aligned}
$$

by the first equality we have that $\mathcal{P}_{A P Q}+\mathcal{P}_{C P Q}-\mathcal{P}_{B P Q}-\mathcal{P}_{D P Q}=0$, applying the definition of Pythagoras difference we have that $\overline{A P}^{2}-\overline{A Q}^{2}+\overline{C P}^{2}-\overline{C Q}^{2}-\overline{B P}^{2}+\overline{B Q}^{2}-\overline{D P}^{2}+\overline{D Q}^{2}=0$

$$
\begin{aligned}
& =\overline{A Q}^{2}+\overline{C Q}^{2}-\overline{B Q}^{2}-\overline{D Q}^{2}-\mathcal{P}_{B A D} \\
& =\overline{A Q}^{2}+\overline{A B}^{2}-\overline{B Q}^{2}-\left(\overline{D Q}^{2}+\overline{A B}^{2}-\overline{C Q}^{2}\right)-\mathcal{P}_{B A D}
\end{aligned}
$$

Given the fact that $A B C D$ is a parallelogram, we have $\overline{A B}^{2}=\overline{C D}^{2}$

$$
\begin{aligned}
& =\overline{B A}^{2}+\overline{Q A}^{2}-\overline{B Q}^{2}-\left(\overline{C D}^{2}+\overline{Q D}^{2}-\overline{C Q}^{2}\right)-\mathcal{P}_{B A D} \\
& =\mathcal{P}_{B A Q}-\mathcal{P}_{C D Q}-\mathcal{P}_{B A D}
\end{aligned}
$$

considering the co-areas [4], we have

$$
=\mathcal{C}_{B A Q}-\mathcal{C}_{C D Q}-\mathcal{C}_{B A D}
$$

Considering the square $A B X_{1} X_{2}$ (see figure 2.23) we have:

$$
\begin{aligned}
& =\nabla A Q X_{2}-\nabla A Q_{1} X_{2}-\nabla B A D \\
& =A X_{2}\left(\left(h_{1}-h_{2}\right)-h_{3}\right) \\
& =A X_{2} \times 0 \\
& =0
\end{aligned}
$$

Q.E.D.


Figure 2.23:

### 2.3.4 Proofs of the Elimination Lemmas

Lemma 28: Let $G(Y)$ be one of the following geometric quantities: $\mathcal{S}_{A B Y}, \mathcal{S}_{A B C Y}, \mathcal{P}_{A B Y}$, or $\mathcal{P}_{A B C Y}$ for distinct points $A, B, C$, and $Y$. For three collinear points $Y, U$, and $V$ it holds

$$
\begin{equation*}
G(Y)=\frac{\overline{U Y}}{\overline{U V}} G(V)+\frac{\overline{Y V}}{\overline{U V}} G(U) \tag{2.2}
\end{equation*}
$$

## Proof of Lemma 28

Case $G(Y)=\mathcal{S}_{A B Y}:$

$$
\begin{aligned}
\mathcal{S}_{A B Y} & =\mathcal{S}_{Y A B} \quad \text { by lemma } 8 \\
& =\frac{\overline{U Y}}{\overline{\overline{U V}}} \mathcal{S}_{V A B}+\frac{\overline{\overline{U V}}}{\overline{\bar{U}}} \mathcal{S}_{U A B} \quad \text { by lemma } 16 ; U, V, \text { and } Y \text { are collinear } \\
& =\frac{\overline{U Y}}{\overline{U V}} \mathcal{S}_{A B V}+\frac{\overline{\overline{U V}}}{\bar{U}} \mathcal{S}_{A B U} \quad \text { by lemma } 8 \\
& =\frac{\overline{U Y}}{\overline{U V}} G(V)+\frac{\overline{\overline{Y V}}}{\overline{U V}} G(U)
\end{aligned}
$$

Case $G(Y)=\mathcal{P}_{A B Y}:$

$$
\begin{aligned}
\mathcal{P}_{A B Y} & =\mathcal{P}_{Y B A} \quad \text { by lemmas } 17,18 \\
& =\overline{\overline{U Y}} \mathcal{P}_{V B A}+\frac{\overline{Y V}}{\overline{\overline{U V}}} \mathcal{P}_{U B A} \quad \text { by lemma } 26 ; U, V, \text { and } Y \text { are collinear } \\
& =\overline{\overline{U Y}} \mathcal{P}_{A B V}+\frac{\overline{\overline{Y V}}}{\overline{\overline{U V}}} \mathcal{P}_{A B U} \quad \text { by lemmas } 3,5 \\
& =\frac{\overline{U Y}}{\overline{U V}} G(V)+\frac{\overline{Y V}}{\overline{U V}} G(U)
\end{aligned}
$$

Case $G(Y)=\mathcal{S}_{A B C Y}:$

$$
\mathcal{S}_{A B C Y}=\mathcal{S}_{A B C}-\mathcal{P}_{A C Y} \quad \text { by definition } 4
$$

$$
\begin{aligned}
& =\mathcal{S}_{A B C}+\frac{\overline{U Y}}{\overline{U V}} \mathcal{S}_{A B C}-\frac{\overline{U Y}}{\overline{U V}} \mathcal{S}_{A B C}+\frac{\overline{Y V}}{\overline{U V}} \mathcal{S}_{A B C}-\frac{\overline{Y V}}{\overline{U V}} \mathcal{S}_{A B C}+\mathcal{S}_{A C Y} \\
& =\left(1-\left(\frac{\overline{U Y}}{\overline{U V}}+\frac{\overline{Y V}}{\overline{U V}}\right) \mathcal{S}_{A B C}+\frac{\overline{U Y}}{\overline{U V}} \mathcal{S}_{A B C}+\frac{\overline{Y V}}{\overline{U V}} \mathcal{S}_{A B C}+\mathcal{S}_{A C Y}\right. \\
& =0+\frac{\overline{U Y}}{\overline{U V}} \mathcal{S}_{A B C}+\frac{\overline{Y V}}{\overline{U V}} \mathcal{S}_{A B C}+\mathcal{S}_{A C Y} \quad U, V, \text { and } Y \text { are collinear } \\
& =\frac{\overline{U Y}}{\overline{U V}} \mathcal{S}_{A B C}+\frac{\overline{Y V}}{\overline{U V}} \mathcal{S}_{A B C}+\mathcal{S}_{Y A C} \quad \text { by lemma } 8 \\
& =\frac{\overline{U Y}}{\overline{\overline{U V}}} \mathcal{S}_{A B C}+\frac{\overline{U Y}}{\overline{U V}} \mathcal{S}_{A C V}+\frac{\overline{Y V}}{\overline{U V}} \mathcal{S}_{A B C}+\frac{\overline{Y V}}{\overline{U V}} \mathcal{S}_{A C U} \quad \text { by lemma } 16 ; U, V, \\
& =\frac{\text { and } Y \text { are collinear }}{\overline{U Y}} \mathcal{S}_{A B C V}+\frac{\overline{Y V}}{\overline{U V}} \mathcal{S}_{A B C U} \quad \text { by definition } 4 \\
& =\frac{\overline{U Y}}{\overline{\overline{U V}}} G(V)+\frac{\overline{Y V}}{\overline{\overline{U V}}} G(U)
\end{aligned}
$$

Case $G(Y)=\mathcal{P}_{A B C Y}:$

$$
\begin{aligned}
\mathcal{P}_{A B C Y} & =\mathcal{P}_{A B Y}-\mathcal{P}_{C B Y} \quad \text { by definition } 5 \\
& =\frac{\overline{U Y}}{\overline{\overline{U V}}} \mathcal{P}_{A B V}+\frac{\overline{\overline{Y V}}}{\overline{\bar{U}}} \mathcal{P}_{A B U}-\left(\frac{\overline{U Y}}{\overline{U V}} \mathcal{P}_{C B V}+\frac{\overline{Y V}}{\overline{\overline{U V}}} \mathcal{P}_{C B U}\right) \\
& =\frac{\overline{U Y}}{\overline{\overline{U V}}}\left(\mathcal{P}_{A B V}-\mathcal{P}_{C B V}\right)+\frac{\overline{Y V}}{\overline{U V}}\left(\mathcal{P}_{A B U}-\mathcal{P}_{C B U}\right) \\
& =\frac{\overline{U Y}}{\overline{U V}} \mathcal{P}_{A B C V}+\frac{\overline{Y V}}{\overline{U V}} \mathcal{P}_{A B C U} \quad \text { by definition } 5 \\
& =\frac{\overline{U Y}}{\overline{U V}} G(V)+\frac{\overline{Y V}}{\overline{U V}} G(U)
\end{aligned}
$$

Q.E.D.

Lemma 29: (EL2) Let $G(Y)$ be a linear geometric quantity and point $Y$ is introduced by the construction (Pratio Y W (Line U V) r). Then it holds

$$
G(Y)=G(W)+r(G(V)-G(U)) .
$$

## Proof of Lemma 29 (EL2)

Take a point $S$ such that $\overline{W S}=\overline{U V}$.


By (2.2) (with $\mathrm{U}:=\mathrm{A} ; \mathrm{V}:=\mathrm{B} ; \mathrm{W}:=\mathrm{U} ; \mathrm{S}:=\mathrm{V})$ :

$$
\begin{aligned}
G(Y) & =\frac{\overline{W Y}}{\overline{W S}} G(S)+\frac{\overline{Y S}}{\overline{W S}} G(W) \quad \frac{\overline{W Y}}{\overline{W S}}=1, \text { by hypothesis } \\
& =r G(S)+\left(\frac{\overline{W Y}-\overline{W S}}{\overline{W S}}\right) G(W) \quad W, Y, S \text { are collinear } \\
& =r G(S)+(1-r) G(W)
\end{aligned}
$$

By lemmas $15\left(\mathcal{S}_{A P Q}=\mathcal{S}_{B P Q}+\mathcal{S}_{D P Q}-\mathcal{S}_{C P Q}\right)$ and $27,\left(\mathcal{P}_{A P Q}=\mathcal{P}_{B P Q}+\mathcal{P}_{D P Q}-\mathcal{P}_{C P Q}\right)$ considering the parallelogram $U V S W$ and the points $W$ and $Y$ we have $G(S)=G(W)+$ $G(V)-G(U)$. Substituting this into the above equation, we obtain the result.

$$
\begin{aligned}
G(Y) & =r G(S)+(1-r) G(W) \\
& =r(G(W)+G(V)-G(U))+(1-r) G(W) \\
& =r G(W)-r G(W)+G(W)+r(G(V)-G(U)) \\
& =G(W)+r(G(V)-G(U))
\end{aligned}
$$

Notice that we need the ndg. condition $U \neq V$.
Q.E.D.

Lemma 30: (EL3) Let $G(Y)$ be a linear geometric quantity and point $Y$ is introduced by the construction (Inter Y (Line U V) (Line P Q). Then it holds

$$
G(Y)=\frac{\mathcal{S}_{U P Q} G(V)-\mathcal{S}_{V P Q} G(U)}{\mathcal{S}_{U P V Q}}
$$

## Proof of Lemma 30 (EL3)



By the co-side theorem (with $\mathrm{P}:=\mathrm{U} ; \mathrm{Q}:=\mathrm{V} ; \mathrm{A}:=\mathrm{P} ; \mathrm{B}:=\mathrm{Q} ; \mathrm{M}:=\mathrm{Y}$ ), $\frac{\overline{\overline{U Y}}}{\overline{U V}}=\frac{\mathcal{S}_{U P Q}}{\mathcal{S}_{U P V Q}}, \frac{\overline{Y V}}{\overline{U V}}=$ $-\frac{\overline{V Y}}{\overline{U V}}=-\frac{\mathcal{S}_{V P Q}}{\mathcal{S}_{U P V Q}}$. Substituting these into equation (2.2), we prove the result.

## Q.E.D.

Lemma 31: (EL4) Let $G(Y)$ be a linear geometric quantity $\left(\neq \mathcal{P}_{A Y B}\right)$ and point $Y$ is introduced by the construction (Foot Y P (Line U V)). Then it holds

$$
G(Y)=\frac{\mathcal{P}_{P U V} G(V)+\mathcal{P}_{P V U} G(U)}{\mathcal{P}_{U V U}}
$$

## Proof of Lemma 31 (EL4)



By lemma 24 (with $\mathrm{A}:=\mathrm{U} ; \mathrm{B}:=\mathrm{V} ; \mathrm{D}:=\mathrm{Y}$ ), $\frac{\overline{U Y}}{\overline{U V}}=\frac{\mathcal{P}_{P U V}}{2 \overline{U V^{2}}}, \frac{\overline{Y V}}{\overline{U V}}=\frac{\mathcal{P}_{P V U}}{2 \overline{U V^{2}}}$. Substituting these into (2.2), we prove the result.
Q.E.D.

Lemma 32: (EL5) Let $G(Y)=\mathcal{P}_{A Y B}$ and point $Y$ is introduced by the construction (Foot Y P (Line U V)). Then it holds

$$
G(Y)=\frac{\mathcal{P}_{P U V}}{\mathcal{P}_{U V U}} G(V)+\frac{\mathcal{P}_{P V U}}{\mathcal{P}_{U V U}} G(U)-\frac{\mathcal{P}_{P U V} \times \mathcal{P}_{P V U}}{\mathcal{P}_{U V U}} .
$$

Proof of Lemma 32 (EL5) By lemma 26 (with $\mathrm{R}:=\mathrm{Y} ; \mathrm{P}:=\mathrm{U} ; \mathrm{Q}:=\mathrm{V}$ ), for three collinear points $Y, U$, and $V$, we have $r_{1}=\frac{\overline{U Y}}{\overline{U V}}, r_{2}=\frac{\overline{Y V}}{\overline{U V}}$, and $\mathcal{P}_{A Y B}=r_{1} \mathcal{P}_{A V B}+r_{2} \mathcal{P}_{A U B}-r_{1} r_{2} \mathcal{P}_{U V U}$. That is,

$$
\mathcal{P}_{A Y B}=\frac{\overline{U Y}}{\overline{U V}} \mathcal{P}_{A V B}+\frac{\overline{Y V}}{\overline{U V}} \mathcal{P}_{A U B}-\frac{\overline{U Y}}{\overline{U V}} \times \frac{\overline{Y V}}{\overline{U V}} \mathcal{P}_{U V U}
$$

By hypothesis point $Y$ is the foot on $U V$ of a line passing by $P$, then by lemma 24 (with $\mathrm{A}:=\mathrm{U} ; \mathrm{D}:=\mathrm{Y} ; \mathrm{B}:=\mathrm{V})$ we have:

$$
\mathcal{P}_{A Y B}=\frac{\mathcal{P}_{P U V}}{2 \overline{U V}^{2}} \mathcal{P}_{A V B}+\frac{\mathcal{P}_{P V U}}{2 \overline{U V}^{2}} \mathcal{P}_{A U B}-\frac{\mathcal{P}_{P U V}}{2 \overline{U V}^{2}} \frac{\mathcal{P}_{P V U}}{2 \overline{U V}^{2}} \mathcal{P}_{U V U}
$$

By lemma 20 we have that $\mathcal{P}_{U V U}=2 \overline{V U}^{2}=2 \overline{U V}^{2}$, then we have:

$$
\begin{aligned}
& \mathcal{P}_{A Y B}=\frac{\mathcal{P}_{P U V}}{\mathcal{P}_{U V U}} \mathcal{P}_{A V B}+\frac{\mathcal{P}_{P V U}}{\mathcal{P}_{U V U}} \mathcal{P}_{A U B}-\frac{\mathcal{P}_{P U V} \times \mathcal{P}_{P V U}}{2 \mathcal{P}_{U V U}} \mathcal{P}_{U V U} \\
& \mathcal{P}_{A Y B}=\frac{\mathcal{P}_{P U V}}{\mathcal{P}_{U V U}} \mathcal{P}_{A V B}+\frac{\mathcal{P}_{P V U}}{\mathcal{P}_{U V U}} \mathcal{P}_{A U B}-\frac{\mathcal{P}_{P U V} \times \mathcal{P}_{P V U}}{\mathcal{P}_{U V U}}
\end{aligned}
$$

Q.E.D.

Lemma 33: (EL6) Let $G(Y)=\mathcal{P}_{A Y B}$ and point $Y$ is introduced by the construction (INTER
Y (Line U V) (Line P Q)). Then it holds

$$
G(Y)=\frac{\mathcal{S}_{U P Q}}{\mathcal{S}_{U P V Q}} G(V)+\frac{\mathcal{S}_{V P Q}}{\mathcal{S}_{U P V Q}} G(U)-\frac{\mathcal{S}_{U P Q} \times \mathcal{S}_{V P Q} \times \mathcal{P}_{U V U}}{\mathcal{S}_{U P V Q}^{2}}
$$

## Proof of Lemma 33 (EL6)

By lemma 26 (with $\mathrm{R}:=\mathrm{Y} ; \mathrm{P}:=\mathrm{U} ; \mathrm{Q}:=\mathrm{V}$ ), for three collinear points $Y, U$, and $V$, we have $r_{1}=\frac{\overline{U Y}}{U V}, r_{2}=\frac{\overline{Y V}}{U V}$, and $\mathcal{P}_{A Y B}=r_{1} \mathcal{P}_{A V B}+r_{2} \mathcal{P}_{A U B}-r_{1} r_{2} \mathcal{P}_{U V U}$. That is,

$$
\mathcal{P}_{A Y B}=\frac{\overline{U Y}}{\overline{U V}} \mathcal{P}_{A V B}+\frac{\overline{Y V}}{\overline{U V}} \mathcal{P}_{A U B}-\frac{\overline{U Y}}{\overline{U V}} \overline{\overline{U V}} \mathcal{P}_{U V U} .
$$

By hypothesis point $Y$ is the intersection of $U V$ with $P Q$, then by lemma 7 (with A:=P; $\mathrm{B}:=\mathrm{Q} ; \mathrm{P}:=\mathrm{U} ; \mathrm{Q}:=\mathrm{V} ; \mathrm{M}:=\mathrm{Y})$, we have:

$$
\begin{aligned}
\mathcal{P}_{A Y B} & =\frac{\mathcal{S}_{U P Q}}{\mathcal{S}_{U P V Q}} \mathcal{P}_{A V B}+\frac{\mathcal{S}_{V P Q}}{\mathcal{S}_{U P V Q}} \mathcal{P}_{A U B}-\frac{\mathcal{S}_{U P Q}}{\mathcal{S}_{U P V Q}} \frac{\mathcal{S}_{V P Q}}{\mathcal{S}_{U P V Q}} \mathcal{P}_{U V U} \\
\mathcal{P}_{A Y B} & =\frac{\mathcal{S}_{U P Q}}{\mathcal{S}_{U P V Q}} \mathcal{P}_{A V B}+\frac{\mathcal{S}_{V P Q}}{\mathcal{S}_{U P V Q}} \mathcal{P}_{A U B}-\frac{\mathcal{S}_{U P Q} \times \mathcal{S}_{V P Q} \times \mathcal{P}_{U V U}}{\mathcal{S}_{U P V Q}^{2}}
\end{aligned}
$$

Q.E.D.

Lemma 34: (EL7) Let $Y$ be introduced by (Pratio Y W (Line U V) r). Then it holds:

$$
\mathcal{P}_{A Y B}=\mathcal{P}_{A W B}+r\left(\mathcal{P}_{A V B}-\mathcal{P}_{A U B}+2 \mathcal{P}_{W U V}\right)-r(1-r) \mathcal{P}_{U V U} .
$$

## Proof of Lemma 34 (EL7)


with $\overline{W S}=\overline{U V}$.
By lemma 27[A:=U;B:=V;C:=S;D:=W;P:=A;Q:=B] we have

$$
\begin{aligned}
\mathcal{P}_{A U B}+\mathcal{P}_{A S B} & =\mathcal{P}_{A V B}+\mathcal{P}_{A W B}+2 \mathcal{P}_{V U W} \\
\mathcal{P}_{A S B} & =-\mathcal{P}_{A U B}+\mathcal{P}_{A V B}+\mathcal{P}_{A W B}+2 \mathcal{P}_{V U W}
\end{aligned}
$$

We have to eliminate the point $S$.

with $r_{1}=\frac{\overline{W S}}{\overline{W Y}}, r_{2}=\frac{\overline{S Y}}{\overline{W Y}}$, that is $r_{1}=\frac{1}{r}$ and $r_{2}=\frac{\overline{W Y}-\overline{W S}}{\overline{W Y}}=1-\frac{1}{r}$.
By lemma $26[\mathrm{R}:=\mathrm{S} ; \mathrm{P}:=\mathrm{W} ; \mathrm{Q}:=\mathrm{Y}]$ we have:

$$
\mathcal{P}_{A S B}=r_{1} \mathcal{P}_{A Y B}+r_{2} \mathcal{P}_{A W B}-r_{1} r_{2} \mathcal{P}_{W Y W}
$$

Then we have:

$$
\begin{aligned}
& r_{1} \mathcal{P}_{A Y B}+r_{2} \mathcal{P}_{A W B}-r_{1} r_{2} \mathcal{P}_{W Y W}=-\mathcal{P}_{A U B}+\mathcal{P}_{A V B}+\mathcal{P}_{A W B}+2 \mathcal{P}_{V U W} \\
& r_{1} \mathcal{P}_{A Y B}=-r_{2} \mathcal{P}_{A W B}+r_{1} r_{2} \mathcal{P}_{W Y W}-\mathcal{P}_{A U B}+\mathcal{P}_{A V B}+\mathcal{P}_{A W B}+ \\
& +2 \mathcal{P}_{V U W} \\
& \frac{1}{r} \mathcal{P}_{A Y B}=-\left(1-\frac{1}{r}\right) \mathcal{P}_{A W B}+\frac{1}{r}\left(1-\frac{1}{r}\right) \mathcal{P}_{W Y W}-\mathcal{P}_{A U B}+\mathcal{P}_{A V B}+ \\
& +\mathcal{P}_{A W B}+2 \mathcal{P}_{V U W} \\
& \mathcal{P}_{A Y B}=-r\left(1-\frac{1}{r}\right) \mathcal{P}_{A W B}+\left(1-\frac{1}{r}\right) \mathcal{P}_{W Y W}-r \mathcal{P}_{A U B}+r \mathcal{P}_{A V B}+ \\
& +r \mathcal{P}_{A W B}+2 r \mathcal{P}_{V U W} \\
& \mathcal{P}_{A Y B}=-r \mathcal{P}_{A W B}+r \mathcal{P}_{A W B}+\mathcal{P}_{A W B}+\left(1-\frac{1}{r}\right) \mathcal{P}_{W Y W}-r \mathcal{P}_{A U B}+ \\
& +r \mathcal{P}_{A V B}+2 r \mathcal{P}_{V U W} \\
& \mathcal{P}_{A Y B}=\mathcal{P}_{A W B}+r\left(\mathcal{P}_{A V B}-\mathcal{P}_{A U B}+2 \mathcal{P}_{V U W}\right)+\left(1-\frac{1}{r}\right) \mathcal{P}_{W Y W}
\end{aligned}
$$

By lemma 19, and the hypothesis $\frac{\overline{W Y}}{\overline{U V}}=r$, we have:

$$
\mathcal{P}_{W Y W}=2 \overline{W Y}^{2}=2 r^{2} \overline{U V}^{2}=r^{2} \mathcal{P}_{U V U}
$$

So, we can conclude

$$
\begin{aligned}
& \mathcal{P}_{A Y B}=\mathcal{P}_{A W B}+r\left(\mathcal{P}_{A V B}-\mathcal{P}_{A U B}+2 \mathcal{P}_{V U W}\right)+\left(1-\frac{1}{r}\right) \mathcal{P}_{W Y W} \\
& \mathcal{P}_{A Y B}=\mathcal{P}_{A W B}+r\left(\mathcal{P}_{A V B}-\mathcal{P}_{A U B}+2 \mathcal{P}_{V U W}\right)+\left(1-\frac{1}{r}\right) r^{2} \mathcal{P}_{U V U} \\
& \mathcal{P}_{A Y B}=\mathcal{P}_{A W B}+r\left(\mathcal{P}_{A V B}-\mathcal{P}_{A U B}+2 \mathcal{P}_{V U W}\right)-r(1-r) \mathcal{P}_{U V U}
\end{aligned}
$$

by lemma 17

$$
\mathcal{P}_{A Y B}=\mathcal{P}_{A W B}+r\left(\mathcal{P}_{A V B}-\mathcal{P}_{A U B}+2 \mathcal{P}_{W U V}\right)-r(1-r) \mathcal{P}_{U V U}
$$

Q.E.D.

Lemma 35: (EL8) Let $Y$ be introduced by (Tratio Y (Line P Q) r). Then it holds:

$$
\mathcal{S}_{A B Y}=\mathcal{S}_{A B P}-\frac{r}{4} \mathcal{P}_{P A Q B}
$$

Proof of Lemma 35 (EL8) Let $A_{1}$ be the orthogonal projection from $A$ to $P Q$. Then by lemmas 11 and 24:

$$
\frac{\mathcal{S}_{P A Y}}{\mathcal{S}_{P Q Y}}=\frac{\mathcal{S}_{P A_{1} Y}}{\mathcal{S}_{P Q Y}}=\frac{\overline{P A_{1}}}{\overline{P Q}}=\frac{\mathcal{P}_{A_{1} P Q}}{\mathcal{P}_{Q P Q}}=\frac{\mathcal{P}_{A P Q}}{\mathcal{P}_{Q P Q}}
$$

Thus $\mathcal{S}_{P A Y}=\frac{\mathcal{P}_{A P Q}}{\mathcal{P}_{Q P Q}} \mathcal{S}_{P Q Y}=\frac{r}{4} \mathcal{P}_{A P Q}$. Similarly, $\mathcal{S}_{P B Y}=\frac{\mathcal{P}_{B P Q}}{\mathcal{P}_{Q P Q}} \mathcal{S}_{P Q Y}=\frac{r}{4} \mathcal{P}_{B P Q}$. Now $\mathcal{S}_{A B Y}=\mathcal{S}_{A B P}+\mathcal{S}_{P B Y}-\mathcal{S}_{P A Y}=\mathcal{S}_{A B P}-\frac{r}{4} \mathcal{P}_{P A Q B}$.
Q.E.D.

Lemma 36: (EL9) Let $Y$ be introduced by (Tratio Y (Line P Q) r). Then it holds:

$$
\mathcal{P}_{A B Y}=\mathcal{P}_{A B P}-4 r \mathcal{S}_{P A Q B} .
$$

Proof of Lemma 36 (EL9) Let the orthogonal projections from $A$ and $B$ to $P Y$ be $A_{1}$ and $B_{1}$. Then

$$
\frac{\mathcal{P}_{B P A Y}}{\mathcal{P}_{Y P Y}}=\frac{\mathcal{P}_{B_{1} P A_{1} Y}}{\mathcal{P}_{Y P Y}}=\frac{\overline{A_{1} B_{1}}}{\overline{P Y}}=\frac{\mathcal{S}_{P A_{1} Q B_{1}}}{\mathcal{S}_{P Q Y}}=\frac{\mathcal{S}_{P A Q B}}{\mathcal{S}_{P Q Y}} .
$$

Since $P Y \perp P Q, S_{P Q Y}^{2}=\frac{1}{4} \overline{P Q}^{2} \times \overline{P Y}^{2}$. Then $\mathcal{P}_{Y P Y}=2 \overline{P Y}^{2}=4 r \mathcal{S}_{P Q Y}$. Therefore $\mathcal{P}_{A B Y}=\mathcal{P}_{A B P}-\mathcal{P}_{B P A Y}=\mathcal{P}_{A B P}-4 r \mathcal{S}_{P A Q B}$.
Q.E.D.

Lemma 37: (EL10) Let $Y$ be introduced by (Tratio Y (Line P Q) r). Then it holds

$$
\mathcal{P}_{A Y B}=\mathcal{P}_{A P B}+r^{2} \mathcal{P}_{P Q P}-4 r\left(\mathcal{S}_{A P Q}+\mathcal{S}_{B P Q}\right)
$$

Proof of Lemma 37 (EL10) By lemma 36 (EL9)

$$
\mathcal{P}_{A P Y}=4 r \mathcal{S}_{A P Q}, \quad \mathcal{P}_{B P Y}=4 r \mathcal{S}_{B P Q}
$$

Then

$$
\mathcal{P}_{Y P Y}=2 \overline{P Y}^{2}=4 r \mathcal{S}_{P Q Y}=r^{2} \mathcal{P}_{P Q P}
$$

Then

$$
\mathcal{P}_{A Y B}=\mathcal{P}_{A P B}-\mathcal{P}_{A P Y}-\mathcal{P}_{B P Y}+\mathcal{P}_{Y P Y}=\mathcal{P}_{A P B}+r^{2} \mathcal{P}_{P Q P}-4 r\left(\mathcal{S}_{A P Q}+\mathcal{S}_{B P Q}\right)
$$

Q.E.D.

Lemma 38: (EL11) Let $Y$ be introduced by (Inter Y (Line U V) (Line P Q)). Then it holds

$$
\frac{\overline{A Y}}{\overline{C D}}= \begin{cases}\frac{\mathcal{S}_{A P Q}}{\mathcal{S}_{C P D Q}} & \text { if } A \text { is on } U V \\ \frac{\mathcal{S}_{A U V}}{\mathcal{S}_{C U D V}} & \text { otherwise }\end{cases}
$$

Proof of Lemma 38 (EL11) If $A$ is not on $U V$, let $S$ be a point such that $\overline{A S}=\overline{C D}$.


$$
\frac{\overline{A Y}}{\overline{C D}}=\frac{\overline{A Y}}{\overline{A S}} \quad \text { by construction }
$$

$$
=\frac{\mathcal{S}_{A U V}}{\mathcal{S}_{A U S V}} \quad \text { by lemma EL1 }
$$


$=\frac{\mathcal{S}_{A U V}}{\mathcal{S}_{U A V S}} \quad$ by lemma 21
$=\frac{\mathcal{S}_{A U V}}{\mathcal{S}_{U C V D}} \quad$ by lemma 15

$=\frac{\mathcal{S}_{A U V}}{\mathcal{S}_{C U D V}} \quad$ by lemma 21
If $A$ is on $U V$


$$
\frac{\overline{A Y}}{\overline{C D}}=\frac{\overline{A Y}}{\overline{A S}} \quad \text { by construction }
$$

$$
\begin{aligned}
& =\frac{\mathcal{S}_{A P Q}}{\mathcal{S}_{A P S Q}} \quad \text { by lemma EL1 } \\
& =\frac{\mathcal{S}_{A P Q}}{\mathcal{S}_{C P D Q}}
\end{aligned}
$$

Q.E.D.

Lemma 39: (EL12) Let $Y$ be introduced by (Foot Y P (Line U V)). We assume $D \neq U$; otherwise interchange $U$ and $V$. Then it holds

$$
\frac{\overline{A Y}}{\overline{C D}}= \begin{cases}\frac{\mathcal{P}_{P C A D}}{\mathcal{P}_{C D C}} & \text { if } A \text { is on } U V \\ \frac{\mathcal{S}_{A U V}}{\mathcal{S}_{C U D V}} & \text { otherwise }\end{cases}
$$

Proof of Lemma 39 (EL12) If $A$ is on $U V$, let $T$ be a point such that $\overline{A T}=\overline{C D}$. By lemma 24 and $27 \frac{\overline{A Y}}{\overline{C D}}=\frac{\overline{A Y}}{\overline{A T}}=\frac{\mathcal{P}_{P A T}}{\mathcal{P}_{A T A}}=\frac{\mathcal{P}_{P C A D}}{\mathcal{P}_{C D C}}$.

The second equation is a direct consequence of the co-side theorem.


By the co-side theorem (lemma EL1)
with line $C D$ and $U V$ we have:

$$
\frac{\overline{C Y}}{\overline{C D}}=\frac{\mathcal{S}_{C U V}}{\mathcal{S}_{C U D V}}
$$

and also by the co-side theorem with line $A C$ and $U V$ we have:

$$
\frac{\overline{C Y}}{\overline{A Y}}=\frac{\mathcal{S}_{C U V}}{\mathcal{S}_{A U V}} \Leftrightarrow \overline{A Y}=\frac{\overline{C Y} \mathcal{S}_{A U V}}{\mathcal{S}_{C U V}}
$$

so:

$$
\frac{\overline{A Y}}{\overline{C D}}=\frac{\frac{\overline{C Y} \mathcal{S}_{A U V}}{\mathcal{S}_{C U V}}}{\overline{C D}}=\frac{\overline{C Y}}{\overline{C D}} \times \frac{\mathcal{S}_{A U V}}{\mathcal{S}_{C U V}}=\frac{\mathcal{S}_{C U V}}{\mathcal{S}_{C U D V}} \times \frac{\mathcal{S}_{A U V}}{\mathcal{S}_{C U V}}=\frac{\mathcal{S}_{A U V}}{\mathcal{S}_{C U D V}}
$$

Q.E.D.

Lemma 40: (EL13) Let $Y$ be introduced by (Pratio Y R (Line P Q) r). Then it holds

$$
\frac{\overline{A Y}}{\overline{C D}}= \begin{cases}\frac{\frac{\overline{A R}}{}}{\frac{P Q}{P Q}} & \text { if } A \text { is on } R Y \\ \frac{S_{A P R Q}}{S_{C D}} & \text { otherwise }\end{cases}
$$

Proof of Lemma 40 (EL13) The first case is obvious:


The second case, take points $T$ and $S$ such that $\frac{\overline{R T}}{\overline{P Q}}=1$ and $\frac{\overline{A S}}{C D}=1$. By the co-side theorem, $\frac{\overline{A Y}}{\overline{C D}}=\frac{\overline{A Y}}{\overline{A S}}=\frac{\mathcal{S}_{A R T}}{\mathcal{S}_{A R S T}}=\frac{\mathcal{S}_{A P R Q}}{\mathcal{S}_{C P D Q}}$.
Q.E.D.

Lemma 41: (EL14) Let $Y$ be introduced by (Tratio Y (Line P Q) r). Then it holds

$$
\frac{\overline{A Y}}{\overline{C D}}= \begin{cases}\frac{\mathcal{S}_{A P Q}-\frac{r}{4} \mathcal{P}_{P Q P}}{S_{C P D Q}} & \text { if } A \text { is on } P Y \\ \frac{\mathcal{P}_{A P Q}}{\mathcal{P}_{C P D Q}} & \text { otherwise }\end{cases}
$$

Proof of Lemma 41 (EL14) The second case is a direct consequence of lemma 25
To the first equality we have, if $A$ is on $P Y$, then $\frac{\overline{A Y}}{C D}=\frac{\overline{A P}}{C D}-\frac{\overline{Y P}}{C D}$. By the co-side theorem, $\frac{\overline{A P}}{\overline{C D}}=\frac{\mathcal{S}_{A P Q}}{\mathcal{S}_{C P D Q}} ; \quad \frac{\overline{Y Y}}{\overline{C D}}=\frac{\mathcal{S}_{Y P Q}}{\mathcal{S}_{C P D Q}}=\frac{r \mathcal{P}_{P Q P}}{4 \mathcal{S}_{C P D Q}}$. Now the desired result follows immediately.
Q.E.D.

### 2.3.5 Proofs of the Free Points and Area Coordinates Lemmas

Lemma 42: $\mathcal{S}_{A B C}=\frac{\left(\mathcal{S}_{O V B}-\mathcal{S}_{O V C}\right) \mathcal{S}_{O U A}+\left(\mathcal{S}_{O V C}-\mathcal{S}_{O V A}\right) \mathcal{S}_{O U B}+\left(\mathcal{S}_{O V A}-\mathcal{S}_{O V B}\right) \mathcal{S}_{O U C}}{\mathcal{S}_{O U V}}$.


Figure 2.24: Lemma 42

## Proof of Lemma 42

We have that:

$$
\mathcal{S}_{A B C}=\mathcal{S}_{O A B}+\mathcal{S}_{O B C}-\mathcal{S}_{O A C}
$$

Let $W$ be the intersection of $U V$ and $O C$, then by lemma 30 (EL3) with the point $W$ being introduced by the construction (Inter W (Line U V) (Line O C). Then it holds

$$
\mathcal{S}_{O B C}=\frac{1}{\mathcal{S}_{O U V}}\left(\mathcal{S}_{O B V} \mathcal{S}_{O U C}+\mathcal{S}_{O B U} \mathcal{S}_{O C V}\right)
$$

Similarly, we have

$$
\mathcal{S}_{O A C}=\frac{1}{\mathcal{S}_{O U V}}\left(\mathcal{S}_{O A V} \mathcal{S}_{O U C}+\mathcal{S}_{O A U} \mathcal{S}_{O C V}\right)
$$

and

$$
\mathcal{S}_{O A B}=\frac{1}{\mathcal{S}_{O U V}}\left(\mathcal{S}_{O A V} \mathcal{S}_{O U B}+\mathcal{S}_{O A U} \mathcal{S}_{O B V}\right)
$$

Then, we have

$$
\begin{aligned}
\mathcal{S}_{A B C}= & \\
= & \frac{1}{\mathcal{S}_{O U V}}\left(\mathcal{S}_{O A V} \mathcal{S}_{O U B}+\mathcal{S}_{O A U} \mathcal{S}_{O B V}+\mathcal{S}_{O B V} \mathcal{S}_{O U C}+\mathcal{S}_{O B U} \mathcal{S}_{O C V}-\right. \\
& \left.-\mathcal{S}_{O A V} \mathcal{S}_{O U C}-\mathcal{S}_{O A U} \mathcal{S}_{O C V}\right) \\
= & \frac{1}{\mathcal{S}_{O U V}}\left(\mathcal{S}_{O A U} \mathcal{S}_{O B V}-\mathcal{S}_{O A U} \mathcal{S}_{O C V}+\mathcal{S}_{O A V} \mathcal{S}_{O U B}+\mathcal{S}_{O B U} \mathcal{S}_{O C V}\right. \\
& \left.+\mathcal{S}_{O B V} \mathcal{S}_{O U C}-\mathcal{S}_{O A V} \mathcal{S}_{O U C}\right) \\
= & \frac{\left(\mathcal{S}_{O V B}-\mathcal{S}_{O V C}\right) \mathcal{S}_{O U A}+\left(\mathcal{S}_{O V C}-\mathcal{S}_{O V A}\right) \mathcal{S}_{O U B}+\left(\mathcal{S}_{O V A}-\mathcal{S}_{O V B}\right) \mathcal{S}_{O U C}}{\mathcal{S}_{O U V}}
\end{aligned}
$$

Q.E.D.

Lemma 43: $\overline{A B}^{2}=\frac{\overline{O U}^{2}\left(\mathcal{S}_{O V A}-\mathcal{S}_{O V B}\right)^{2}}{S_{O U V}^{2}}+\frac{\overline{O V}^{2}\left(\mathcal{S}_{O U A}-\mathcal{S}_{O U B}\right)^{2}}{S_{O U V}^{2}}$.

## Proof of Lemma 43



Figure 2.25: Lemma 43

We begin introducing a new point $M$ by construction (INTER M (PLINE A O U) (PLINE B $\mathrm{O} V)$ ). By construction we have $A M \perp M B$, then by lemma $22, \overline{A B}^{2}=\overline{A M}^{2}+\overline{B M}^{2}$.

We can also define an $r_{1}$ such that the construction (PRATIO M B (LINE O V) $r_{1}$ ), with $A \notin B M$ is true, then by the second case of lemma 40 (EL13) with $[\mathrm{R}:=\mathrm{B} ; \mathrm{C}:=\mathrm{O} ; \mathrm{D}:=\mathrm{U}$; $\mathrm{P}:=\mathrm{O} ; \mathrm{Q}:=\mathrm{V} ; \mathrm{A}:=\mathrm{A} ; \mathrm{Y}:=\mathrm{M}]$, we have $\frac{\overline{A M}}{\overline{O U}}=\frac{\mathcal{S}_{A O B V}}{\mathcal{S}_{O O U V}}$, applying definition 4 and lemmas 8,9 , we have $\frac{\overline{A M}}{\overline{O U}}=\frac{\mathcal{S}_{O V A}-\mathcal{S}_{O V B}}{\mathcal{S}_{O U V}}$.

We can also have an $r_{2}$ such that the construction (PRATIO M A (LINE O U) $r_{2}$ ), with $B \notin A M$ is true, then by the second case of lemma 40 (EL13) with $[\mathrm{R}:=\mathrm{A} ; \mathrm{C}:=\mathrm{O} ; \mathrm{D}:=\mathrm{V}$; $\mathrm{P}:=\mathrm{O} ; \mathrm{Q}:=\mathrm{U} ; \mathrm{A}:=\mathrm{B} ; \mathrm{Y}:=\mathrm{M}]$, we have $\overline{\overline{B M}}=\frac{\mathcal{S}_{B O A U}}{\mathcal{S}_{O O V U}}$, and applying definition 4 and lemmas 8 , 9, we have $\frac{\overline{B M}}{\overline{O V}}=-\left(\frac{\mathcal{S}_{O U A}-\mathcal{S}_{O U B}}{\mathcal{S}_{O U V}}\right)$.

Then :

$$
\begin{aligned}
\overline{A B}^{2} & =\overline{A M}^{2}+\overline{B M}^{2} \\
{\overline{A B^{2}}}^{2} & =\overline{A M}^{2} \\
{\overline{\overline{O U}^{2}}}^{2} & \frac{\overline{B M}^{2}}{\overline{O U}^{2}}
\end{aligned}
$$

$\overline{O U}=\overline{O V}$, by hypothesis

$$
\begin{aligned}
& \frac{\overline{A B}^{2}}{\overline{O U}^{2}}=\frac{\overline{A M}^{2}}{\overline{O U}^{2}}+\frac{\overline{B M}^{2}}{\overline{O V}^{2}} \\
& \frac{\overline{A B}^{2}}{\overline{O U}^{2}}=\left(\frac{\mathcal{S}_{O V A}-\mathcal{S}_{O V B}}{S_{O U V}}\right)^{2}+\left(\frac{\mathcal{S}_{O U A}-\mathcal{S}_{O U B}}{S_{O U V}}\right)^{2} \\
& \overline{A B}^{2}=\frac{\overline{O U}^{2}\left(\mathcal{S}_{O V A}-\mathcal{S}_{O V B}\right)^{2}}{S_{O U V}^{2}}+\frac{\overline{O V}^{2}\left(\mathcal{S}_{O U A}-\mathcal{S}_{O U B}\right)^{2}}{S_{O U V}^{2}}
\end{aligned}
$$

Lemma 44: $S_{O U V}^{2}=\frac{\overline{O U}^{2} \overline{O V}^{2}}{4}$.

Proof of Lemma 44 By hypothesis $U O \perp O V$, and given the fact that the square of a signed area is always positive, we have $S_{O U V}^{2}=\left(\frac{\overline{O U} \overline{O V}}{2}\right)^{2}=\frac{\overline{O U}^{2} \overline{O V}^{2}}{4}$.
Q.E.D.

## Bibliography

[1] B. Buchberger, A. Craciun, T. Jebelean, L. Kovacs, T. Kutsia, K. Nakagawa, F. Piroi, N. Popov, J. Robu, M. Rosenkranz, and W. Windsteiger. Theorema: Towards computeraided mathematical theory exploration. Journal of Applied Logic, 4:470-504, 2006.
[2] Shang-Ching Chou. Proving and discovering geometry theorems using Wu's method. PhD thesis, The University of Texas, Austin, December 1985.
[3] Shang-Ching Chou, Xiao-Shan Gao, and Jing-Zhong Zhang. Automated production of traditional proofs for constructive geometry theorems. In Moshe Vardi, editor, Proceedings of the Eighth Annual IEEE Symposium on Logic in Computer Science LICS, pages 48-56. IEEE Computer Society Press, June 1993.
[4] Shang-Ching Chou, Xiao-Shan Gao, and Jing-Zhong Zhang. Machine Proofs in Geometry. World Scientific, Singapore, 1994.
[5] Shang-Ching Chou, Xiao-Shan Gao, and Jing-Zhong Zhang. Automated generation of readable proofs with geometric invariants, I. multiple and shortest proof generation. Journal of Automated Reasoning, 17:325-347, 1996.
[6] Shang-Ching Chou, Xiao-Shan Gao, and Jing-Zhong Zhang. Automated generation of readable proofs with geometric invariants, II. theorem proving with full-angles. Journal of Automated Reasoning, 17:349-370, 1996.
[7] H. Coelho and L. M. Pereira. Automated reasoning in geometry theorem proving with prolog. Journal of Automated Reasoning, 2(4):329-390, 1986.
[8] George E. Collins. Quantifier elimination for real closed fields by cylindrical algebraic decomposition. volume 33 of Lecture Notes In Computer Science, pages 134-183. SpringerVerlag, 1975.
[9] E. W. Elcock. Representation of knowledge in geometry machine. Machine Intelligence, 8:11-29, 1977.
[10] H. Gelernter. Realization of a geometry theorem proving machine. In Proceedings of the International Conference Information Processing, pages 273-282, Paris, June 15-20 1959.
[11] J.G. Greeno, M. E. Magone, and S. Chaiklin. Theory of constructions and set in problem solving. Memory and Cognition, 7(6):445-461, 1979.
[12] Predrag Janičić. GCLC - a tool for constructive euclidean geometry and more than that. In Nobuki Takayama, Andres Iglesias, and Jaime Gutierrez, editors, Proceedings of

International Congress of Mathematical Software (ICMS 2006), number 4151 in Lecture Notes in Artificial Intelligence. Springer-Verlag, 2006.
[13] Predrag Janičić, Julien Narboux, and Pedro Quaresma. The Area Method: a Recapitulation. Journal of Automated Reasoning. submitted.
[14] Predrag Janičić and Pedro Quaresma. System Description: GCLCprover + GeoThms. In Furbach Ulrich and Shankar Natarajan, editors, Automated Reasoning, volume 4130 of Lecture Notes in Artificial Intelligence, pages 145-150. Springer-Verlag, 2006.
[15] D. Kapur. Using gröbner bases to reason about geometry problems. Journal of Symbolic Computation, 2(4):399-408, 1986.
[16] Deepak Kapur. Geometry theorem proving using hilbert's nullstellensatz. In SYMSAC '86: Proceedings of the fifth ACM symposium on Symbolic and algebraic computation, pages 202-208, New York, NY, USA, 1986. ACM Press.
[17] H. Li. Clifford algebra approaches to mechanical geometry theorem proving. In X.-S. Gao and D. Wang, editors, Mathematics Mechanization and Applications, pages 205-299, San Diego, CA, 2000. Academic Press.
[18] Julien Narboux. A decision procedure for geometry in Coq. In Slind Konrad, Bunker Annett, and Gopalakrishnan Ganesh, editors, Proceedings of TPHOLs'2004, volume 3223 of Lecture Notes in Computer Science. Springer-Verlag, 2004.
[19] A.J. Nevis. Plane geometry theorem proving using forward chaining. Artificial Intelligence, 6(1):1-23, 1975.
[20] Judit Robu. Geometry Theorem Proving in the Frame of the Theorema Project. PhD thesis, Johannes Kepler Universität, Linz, September 2002.
[21] Alfred Tarski. A decision method for elementary algebra and geometry. University of California Press, 1951.
[22] The Coq development team. The Coq proof assistant reference manual, Version 8.2. TypiCal Project, 2009.
[23] D. Wang. Reasoning about geometric problems using an elimination method. In J. Pfalzgraf and D. Wang, editors, Automated Practical Reasoning, pages 147-185, New York, 1995. Springer.
[24] Wen-Tsün Wu. On the decision problem and the mechanization of theorem proving in elementary geometry. volume 21, pages 157-179. Scientia Sinica, 1978.
[25] Jing-Zhong Zhang, Shang-Ching Chou, and Xiao-Shan Gao. Automated production of traditional proofs for theorems in euclidean geometry i. the hilbert intersection point theorems. Annals of Mathematics and Artificial Intelligenze, 13:109-137, 1995.

